



15.S14: Global Business of Artificial Intelligence (GBAIR)

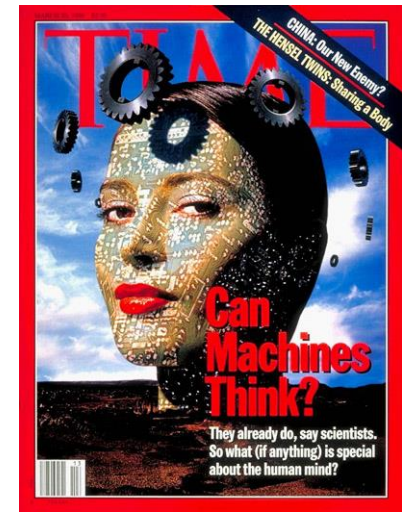
Machine Learning: The Promise, Limitations, and Mystery of Thinking Machines

Lex Fridman

<https://lex.mit.edu>



Artificial Intelligence Technology: Limited or Limitless?

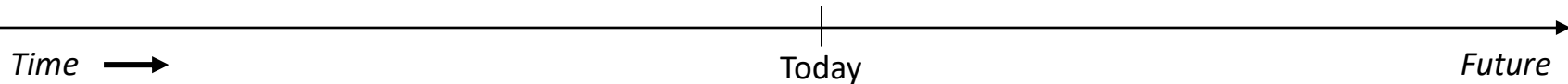


Special Purpose:

Can it achieve a well-defined finite set of goals?

General Purpose:

Can it achieve poorly-defined unconstrained set of goals?



Today's Lecture:

1. Overview current **approaches**
2. Highlight **limitations**
3. Discuss the **potential**
(and marvel at the mystery)

Best current answer:

We Don't Know

Takeaways

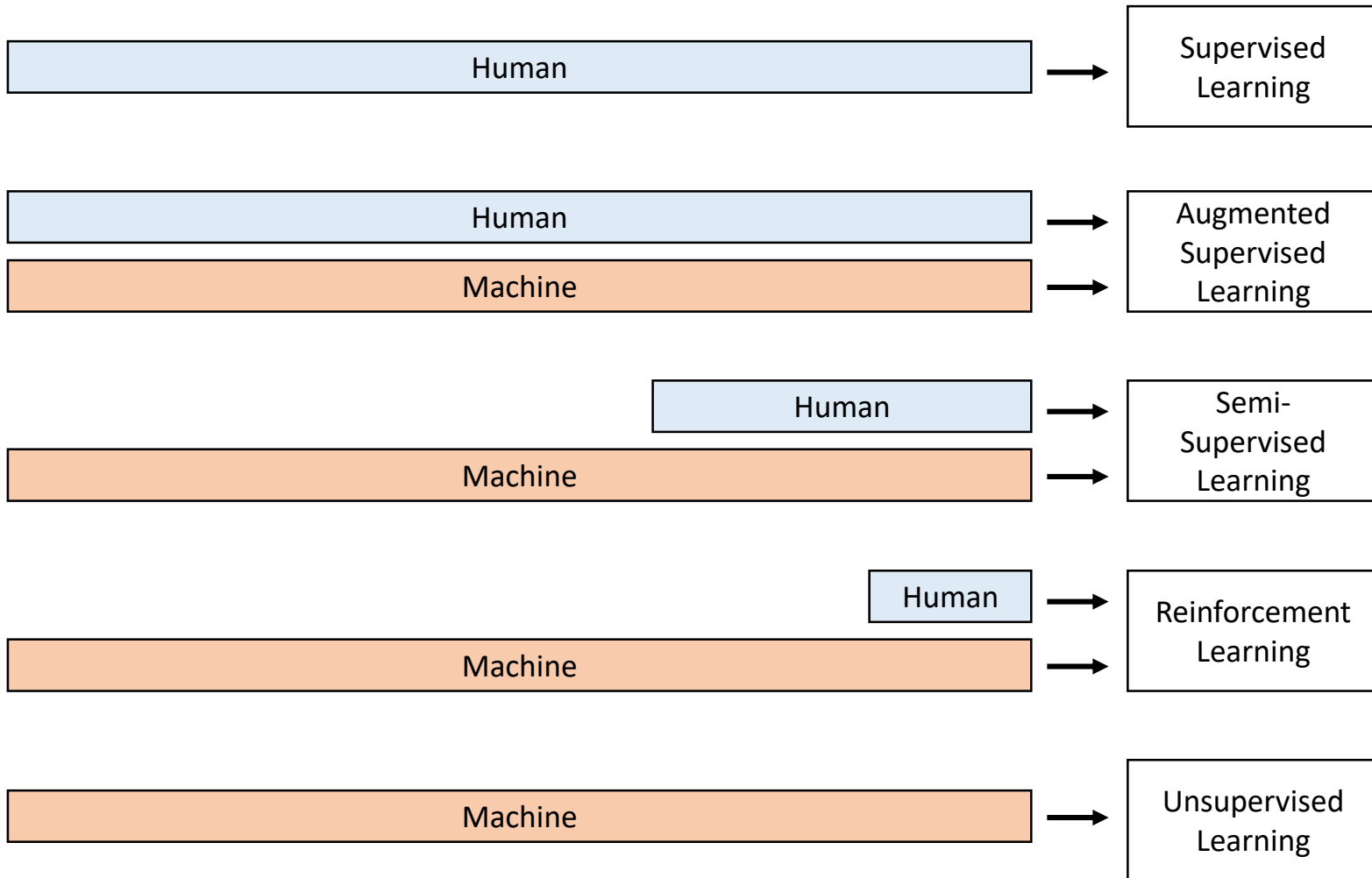
- **Limits:** Machine learning today and tomorrow.
 - Currently **limited** (data, compute, methods)
 - Potentially **limitless** (end-to-end general intelligence)
- **Data:**
 - Representation matters
(deep learning > representation-agnostic learning)
 - Human annotation is needed
(annotated data > big data)
- **Impact:**

Rule of thumb for real-world machine learning:
“If it takes one grad student one month to build a good software prototype, you can make a product out of it. Otherwise, it’s still research.”

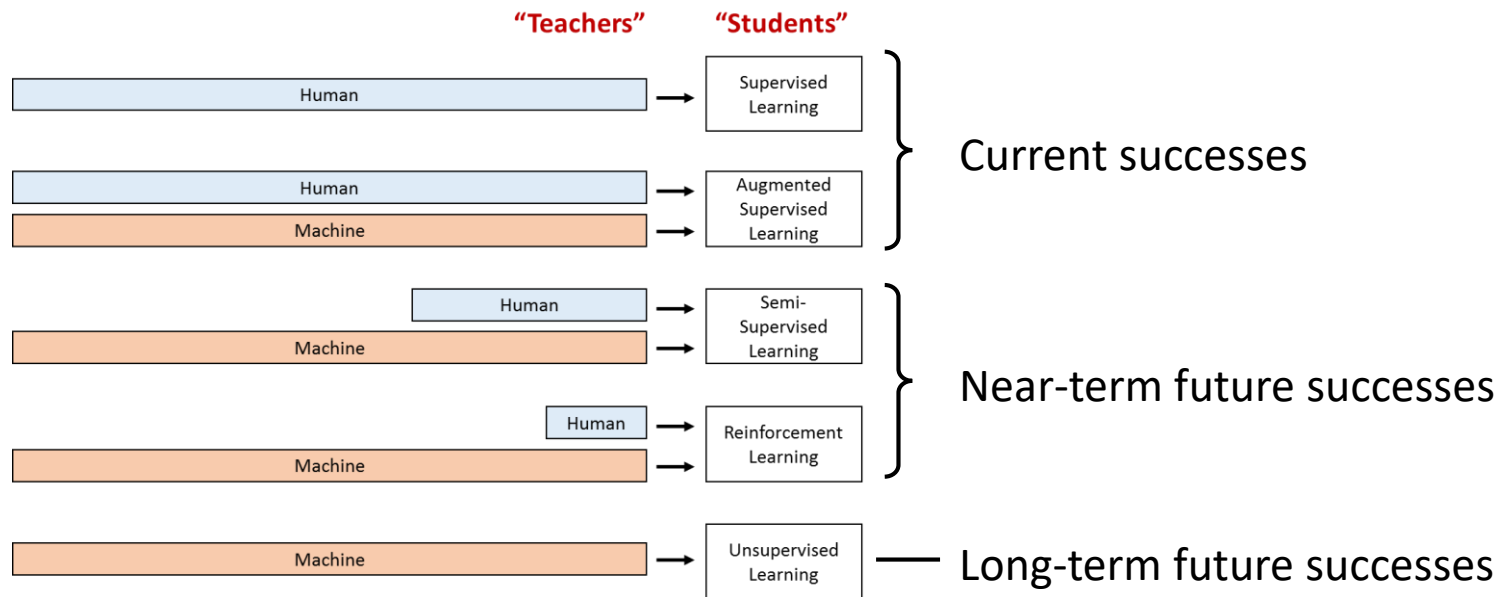
Machine Learning from Human and Machine

“Teachers”

“Students”



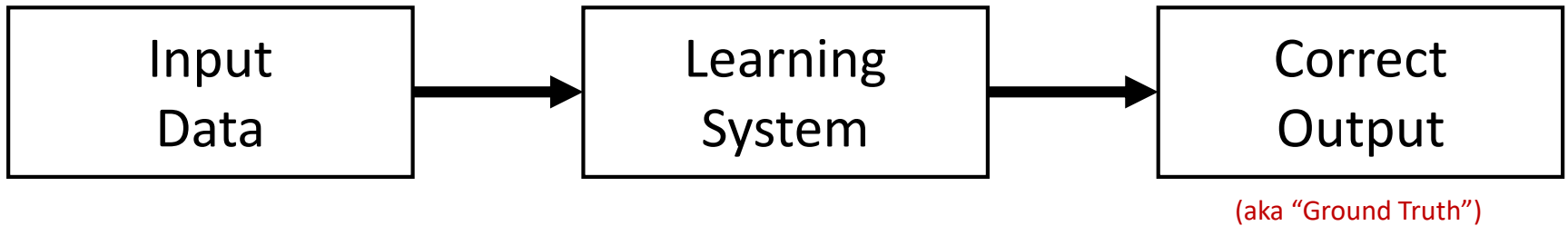
Machine Learning from Human and Machine



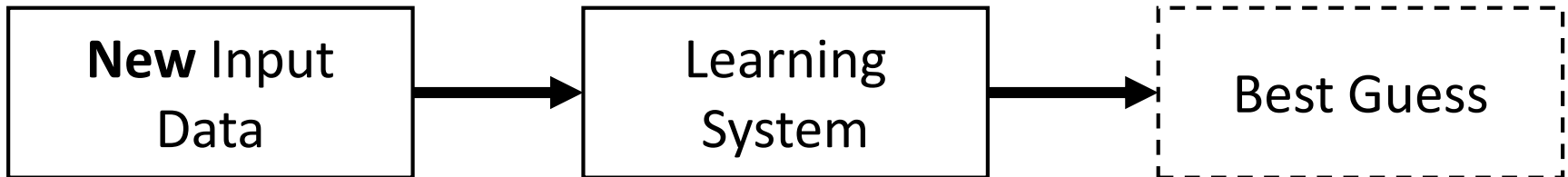
Better Question: Machine Learning: Limited or Limitless?

(PS: for now Machine Learning = Supervised Learning)

Training Stage:

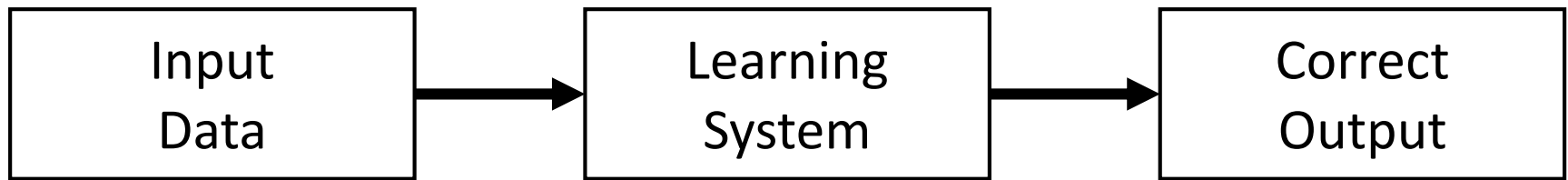


Training Stage:



Open Question: What can't be learned in this way?

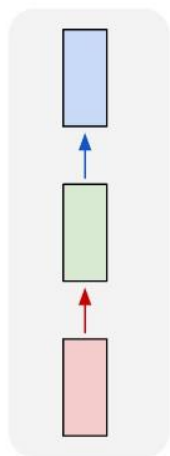
What can we do with Machine Learning?



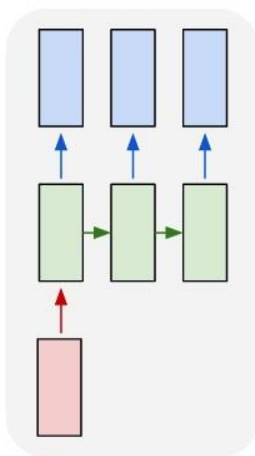
- Number
- Vector of numbers
- Sequence of numbers
- Sequence of vectors of numbers

- Number
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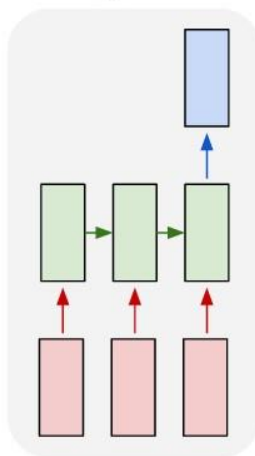
one to one



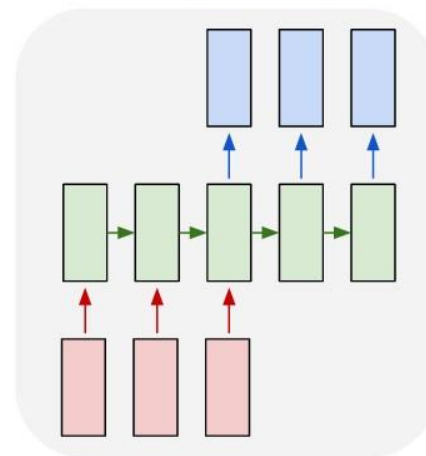
one to many



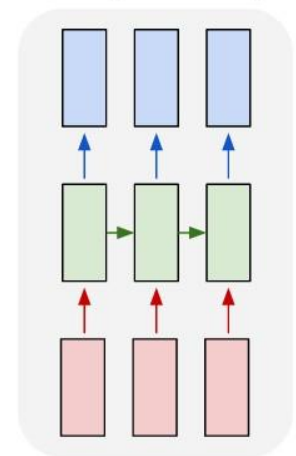
many to one



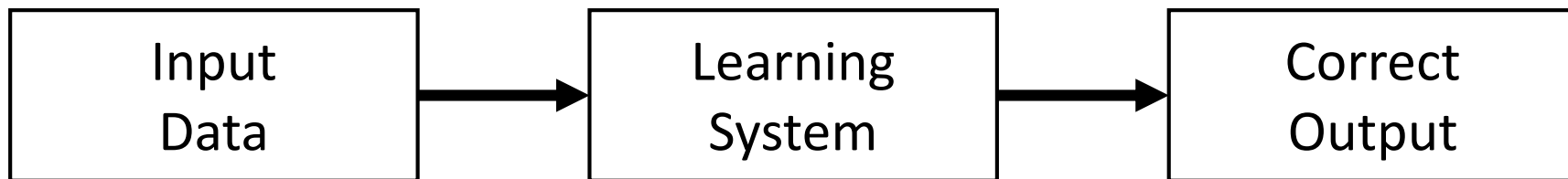
many to many



many to many



What can we do with Machine Learning?



- Images
 - Face
 - Medical
- Text
 - Conversations
 - Articles
 - Questions
- Sounds
 - Voice
- Time series
 - Financial
 - Physiological
- Physical world
 - Location of self
 - Actions of others

...

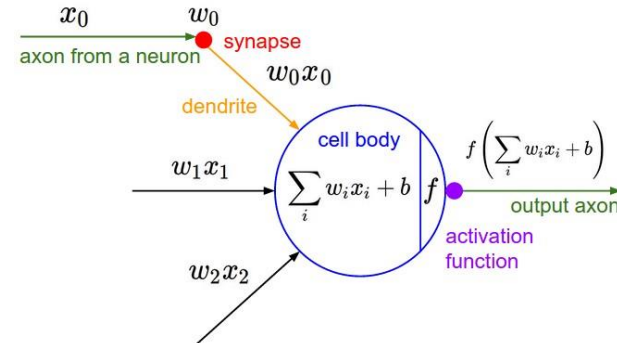
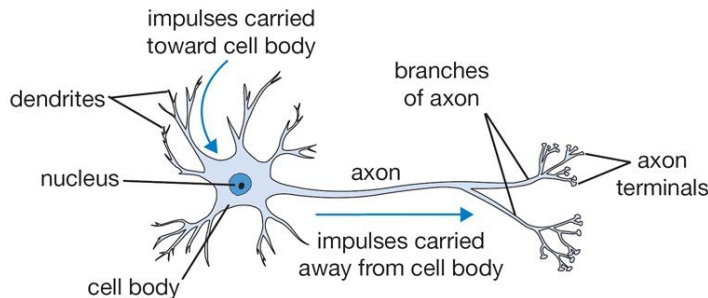
- Nearest Neighbor
- Naïve Bayes
- Support Vector Machines
- Hidden Markov Models
- Ensemble of Methods
- Neural Networks
(aka Deep Learning)

...

- Classification
- Regression
- Sequences
- Text
- Images
- Audio
- Actions

...

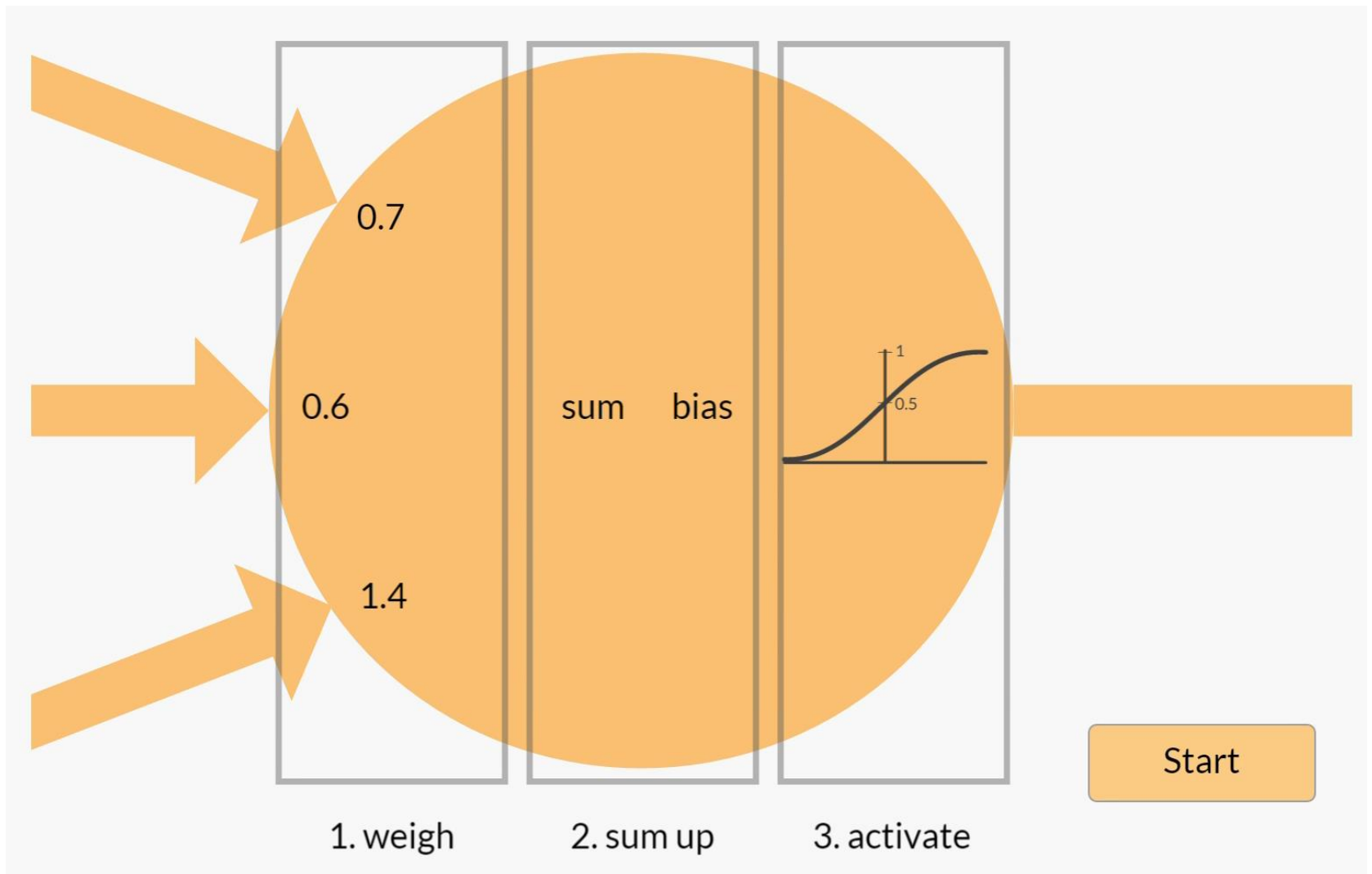
Neuron: Biological Inspiration for Computation



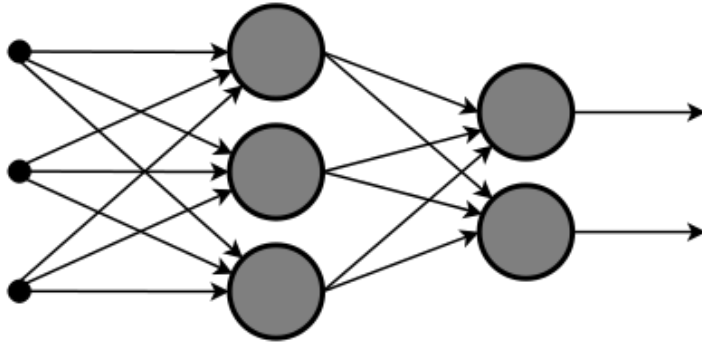
- **Neuron:** computational building block for the brain
- Human brain:
 - ~100-1,000 trillion synapses
- **(Artificial) Neuron:** computational building block for the “neural network”
- (Artificial) neural network:
 - ~1-10 billion synapses

Human brains have ~10,000 computational power than computer brains.

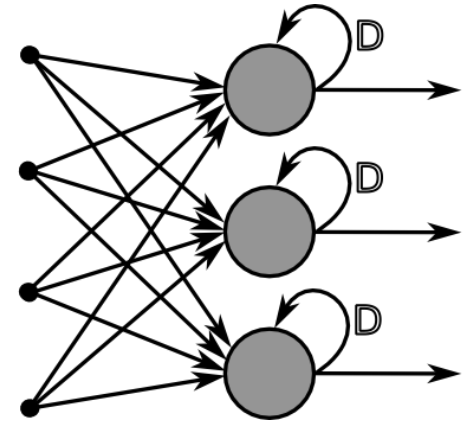
Neuron: Forward Pass



Combining Neurons into Layers



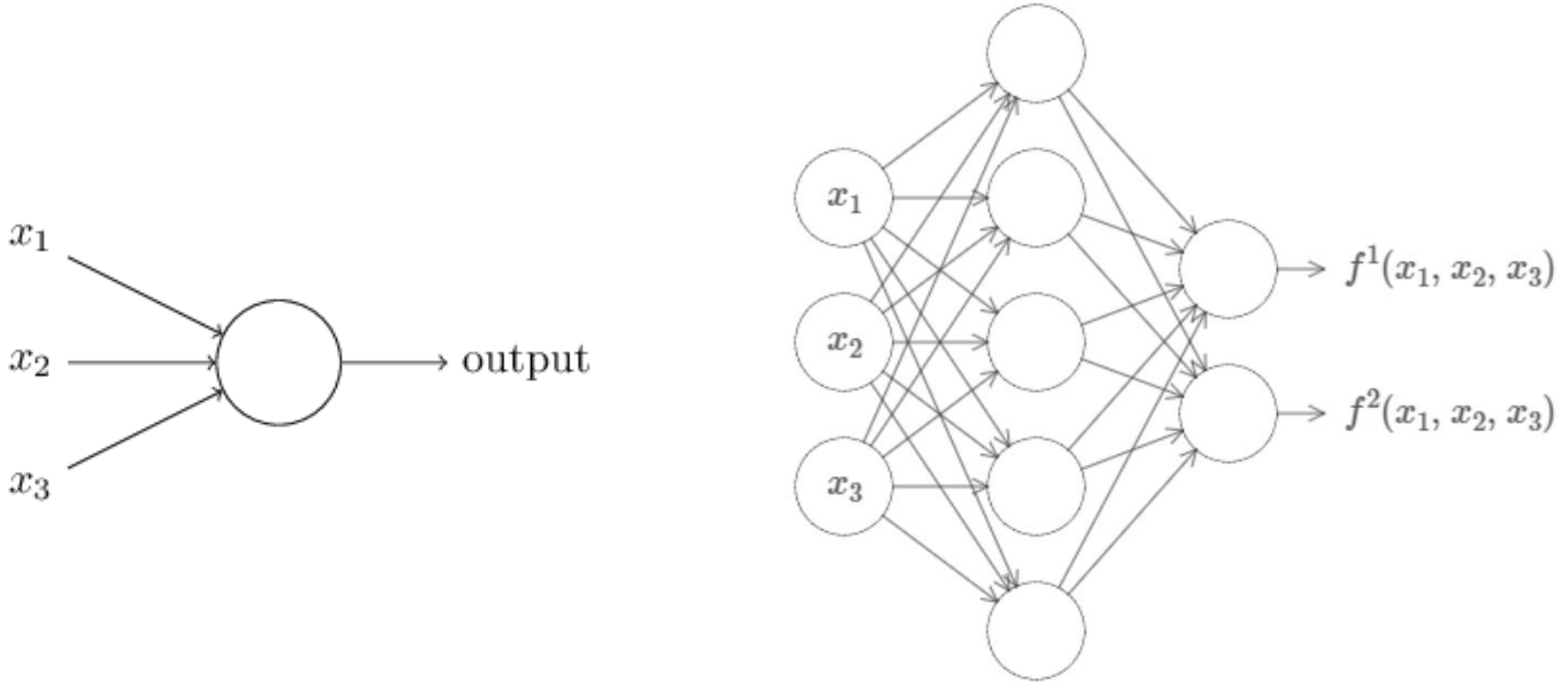
Feed Forward Neural Network



Recurrent Neural Network

- Have state memory
- Are hard to train

Neural Networks are Amazing



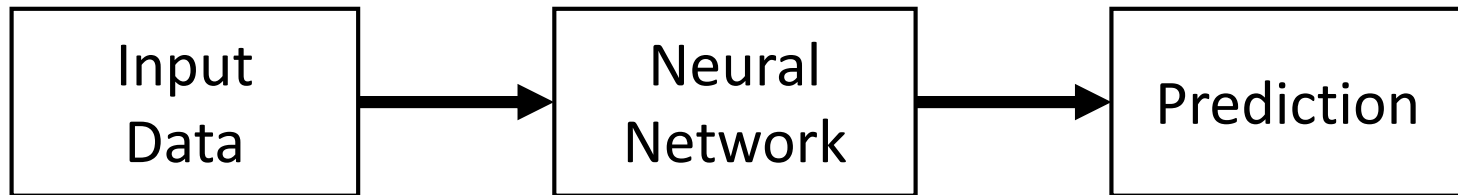
Universality: For any arbitrary function $f(x)$, there exists a neural network that closely approximate it for any input x

Universality is an incredible property!* And it holds for just 1 hidden layer.

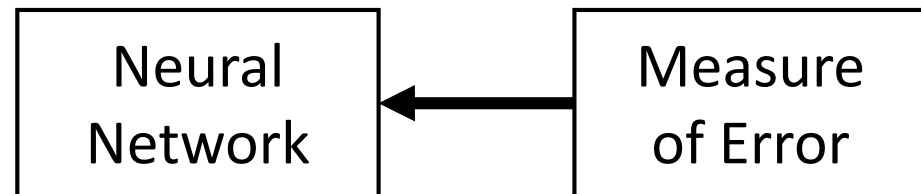
* Given that we have good algorithms for training these networks.

How Neural Networks Learn: Backpropagation

Forward Pass:



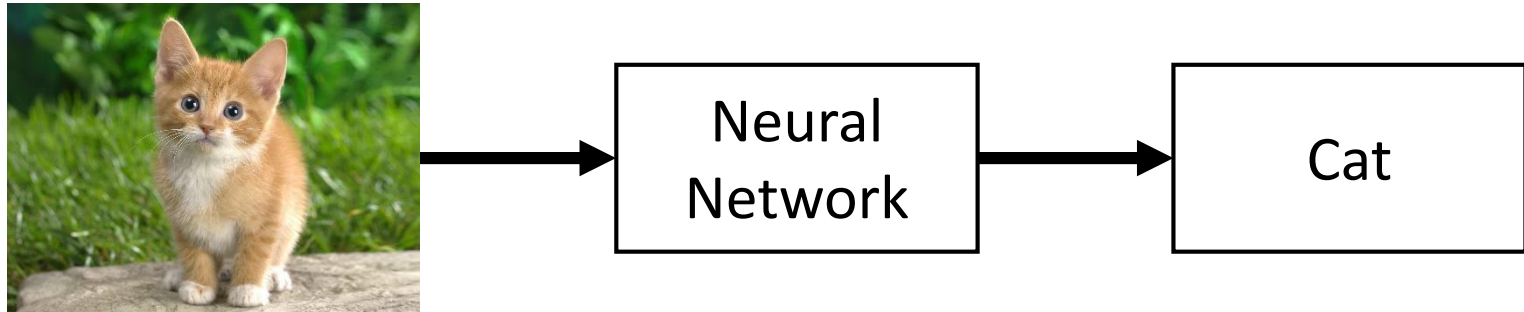
Backward Pass (aka Backpropagation):



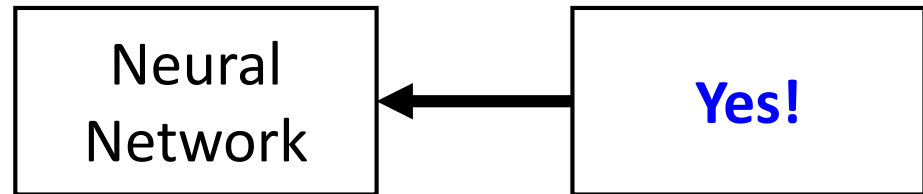
Adjust to Reduce Error

How Neural Networks Learn: Backpropagation

Forward Pass:

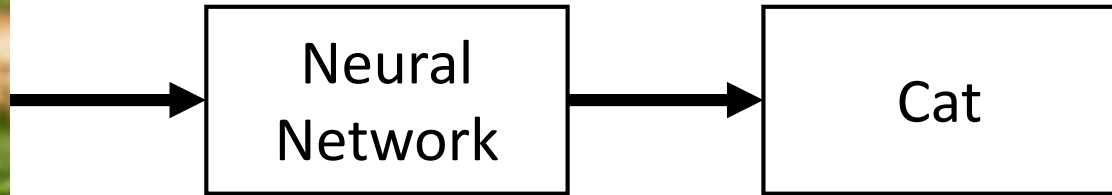
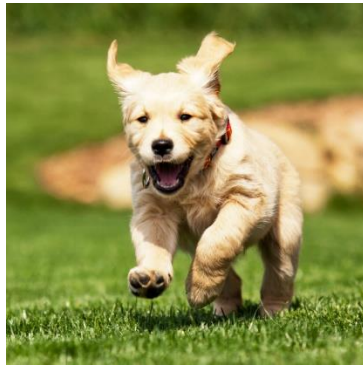


Backward Pass (aka Backpropagation):

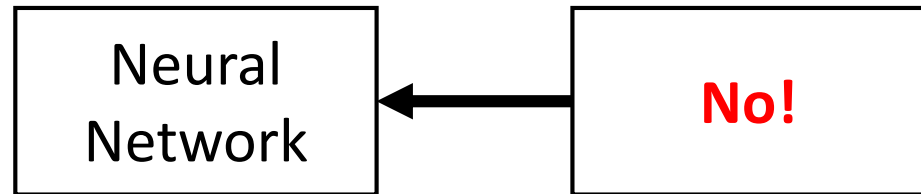


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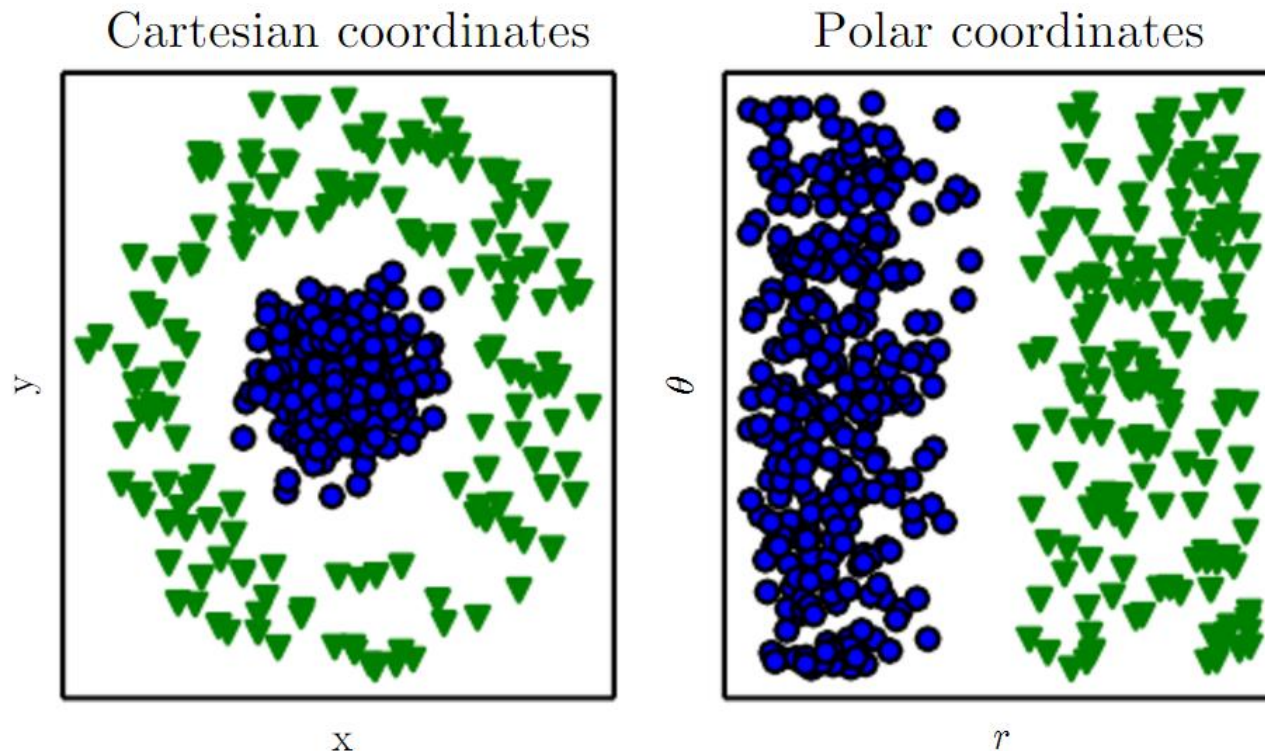
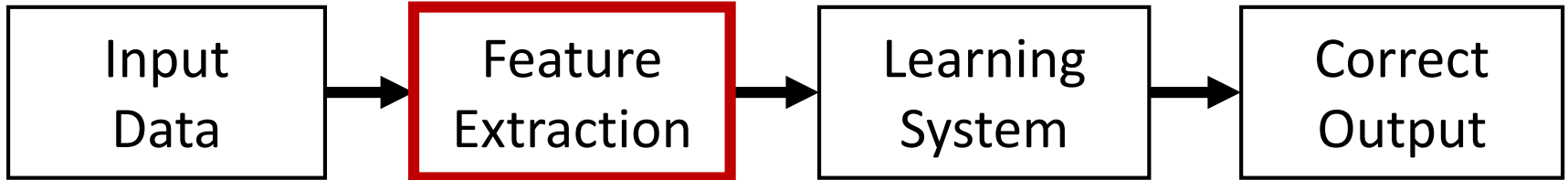


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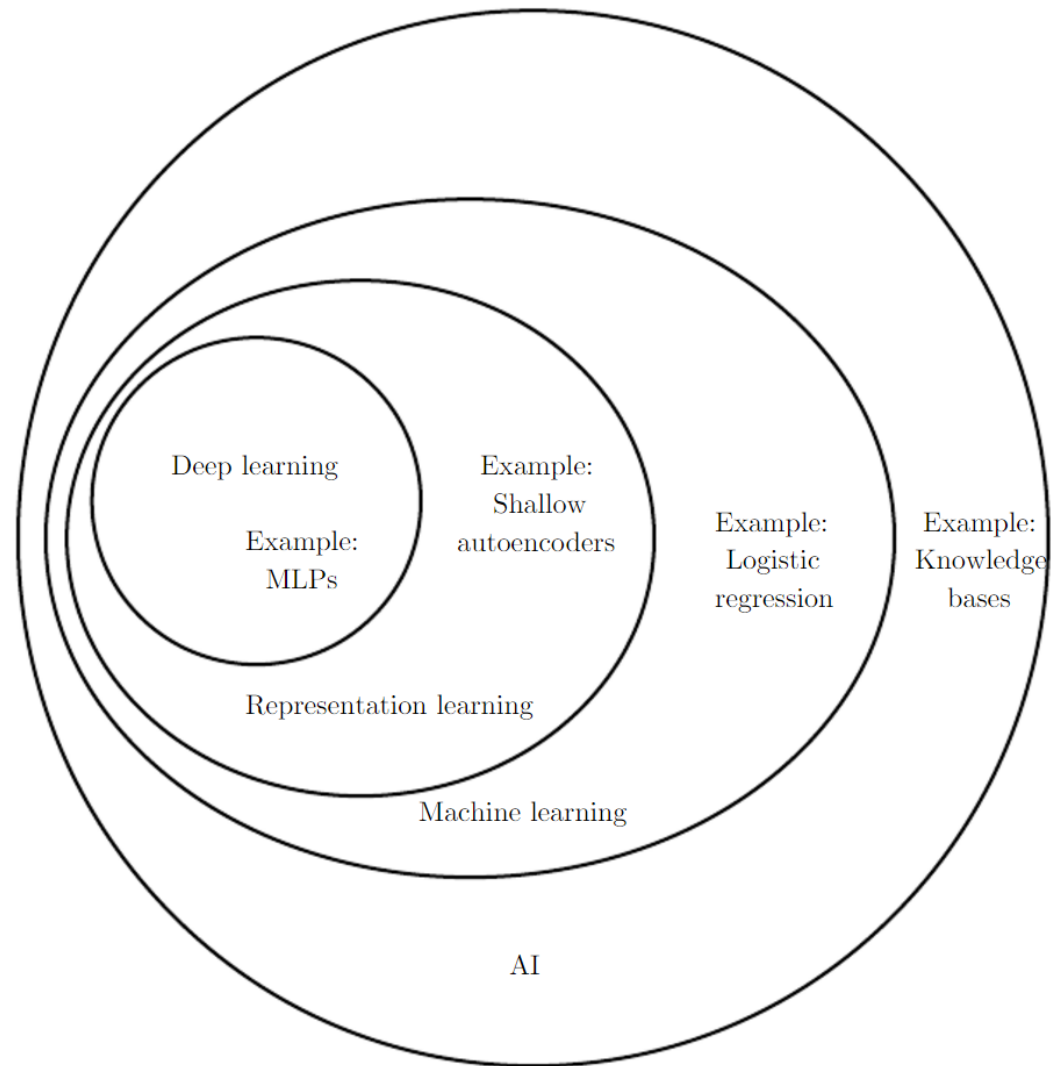


Representation Matters!

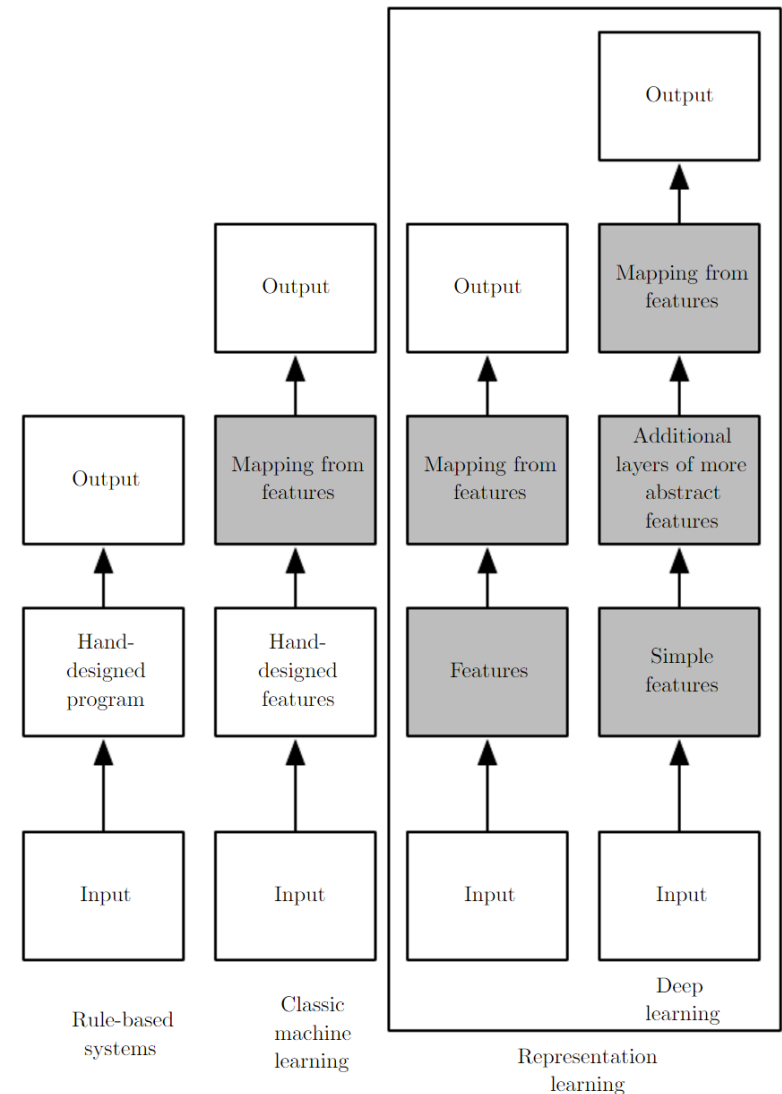
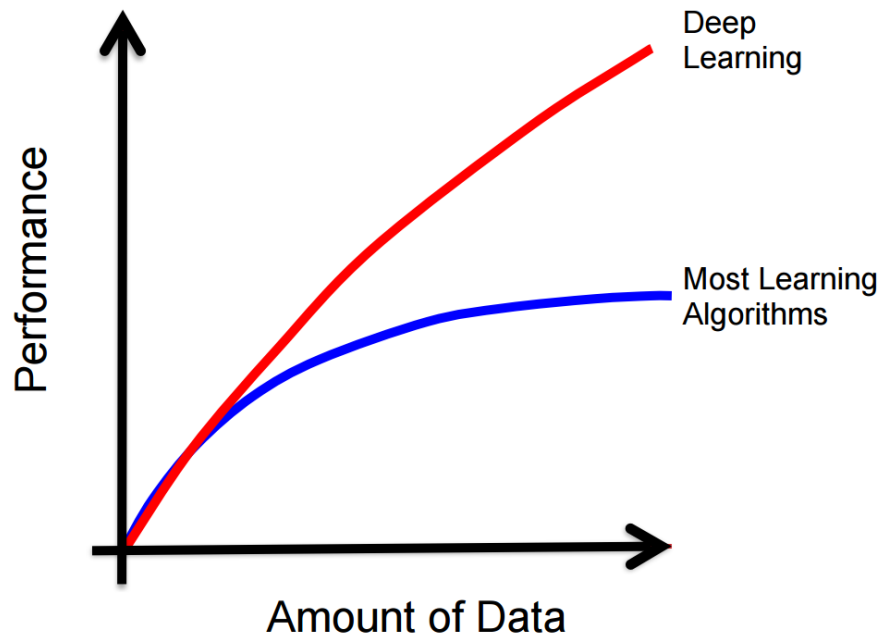
(Representation aka Features)



Deep Learning is **Representation Learning**



Deep Learning: **Scalable** Machine Learning

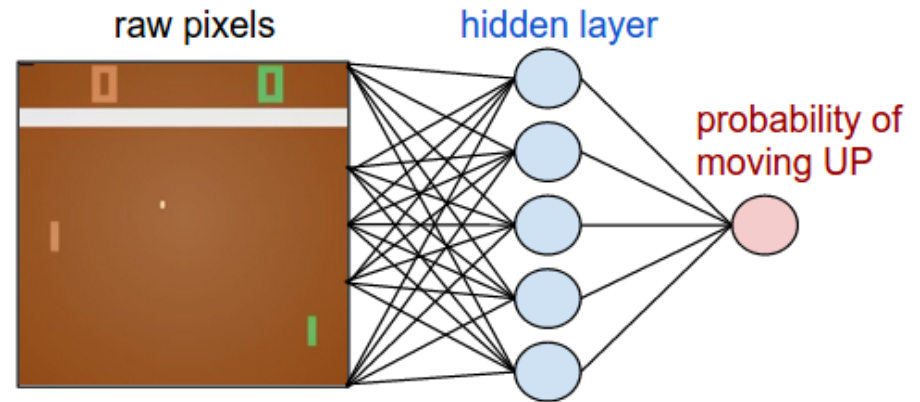


Neural Networks are Amazing: General Purpose Intelligence



Andrej Karpathy. “Deep Reinforcement Learning: Pong from Pixels.” 2016.

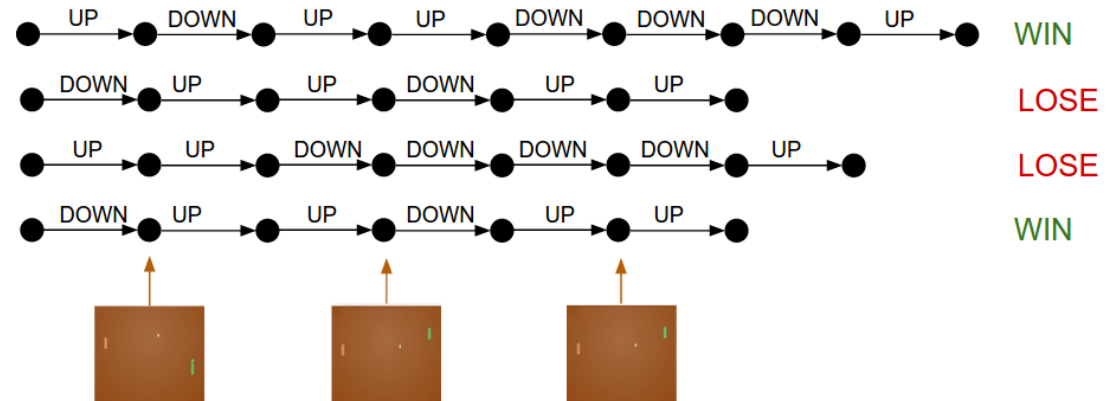
Policy Network:



- 80x80 image (difference image)
- 2 actions: up or down
- 200,000 Pong games

This is a step towards general purpose artificial intelligence!

Neural Networks are Amazing: General Purpose Intelligence



- Every (state, action) pair is **rewarded** when the final result is a **win**.
- Every (state, action) pair is **punished** when the final result is a **loss**.

The fact that this works at all is amazing!

It could be called “general intelligence” but not yet “human-level” intelligence...

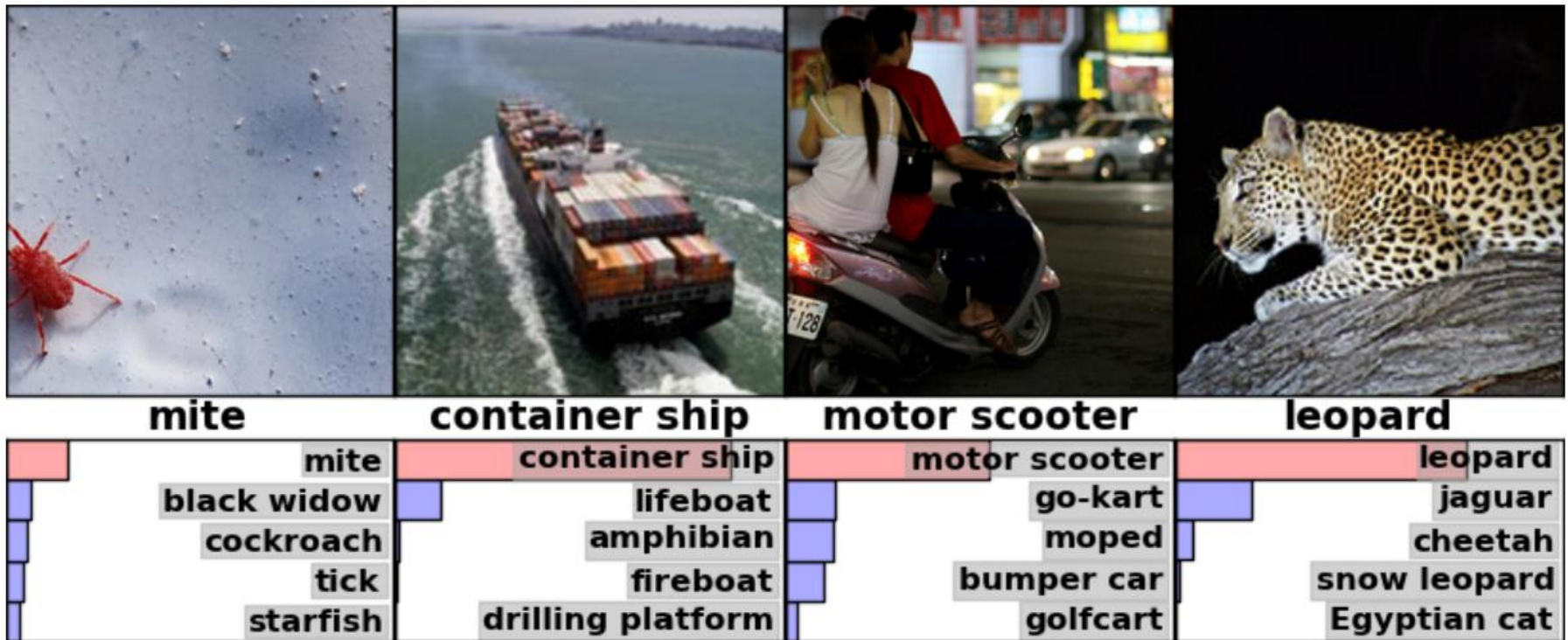
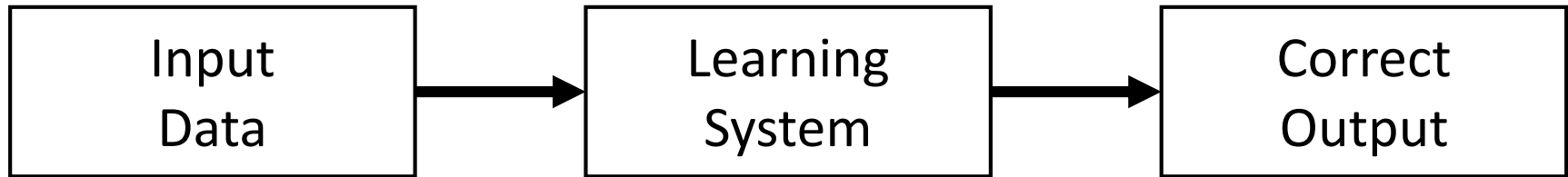
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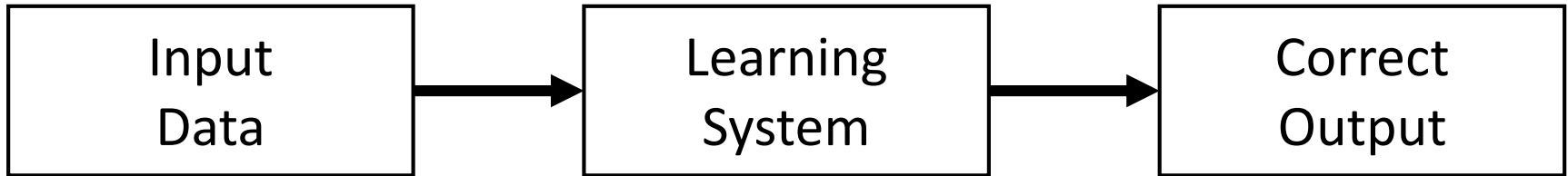
What can we do with Machine Learning?

Object Recognition / Image Classification



What can we do with Machine Learning?

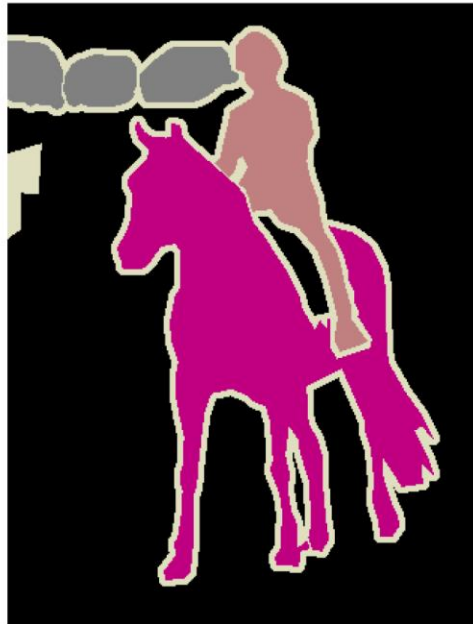
Image Segmentation



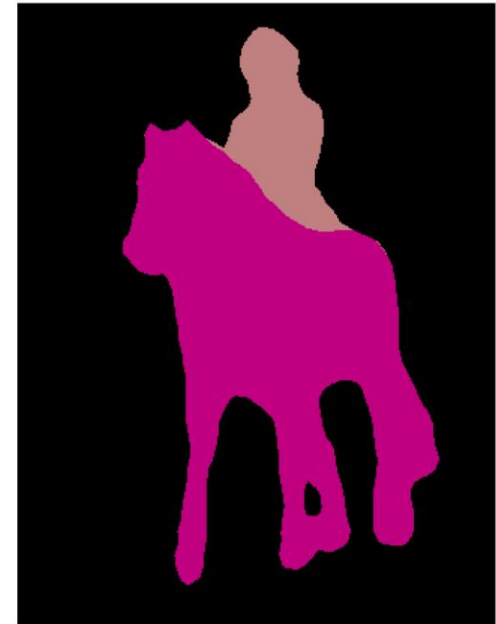
Original



Ground Truth

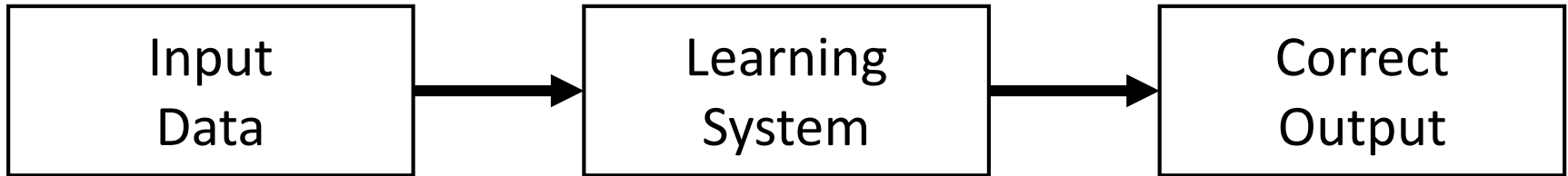


FCN-8



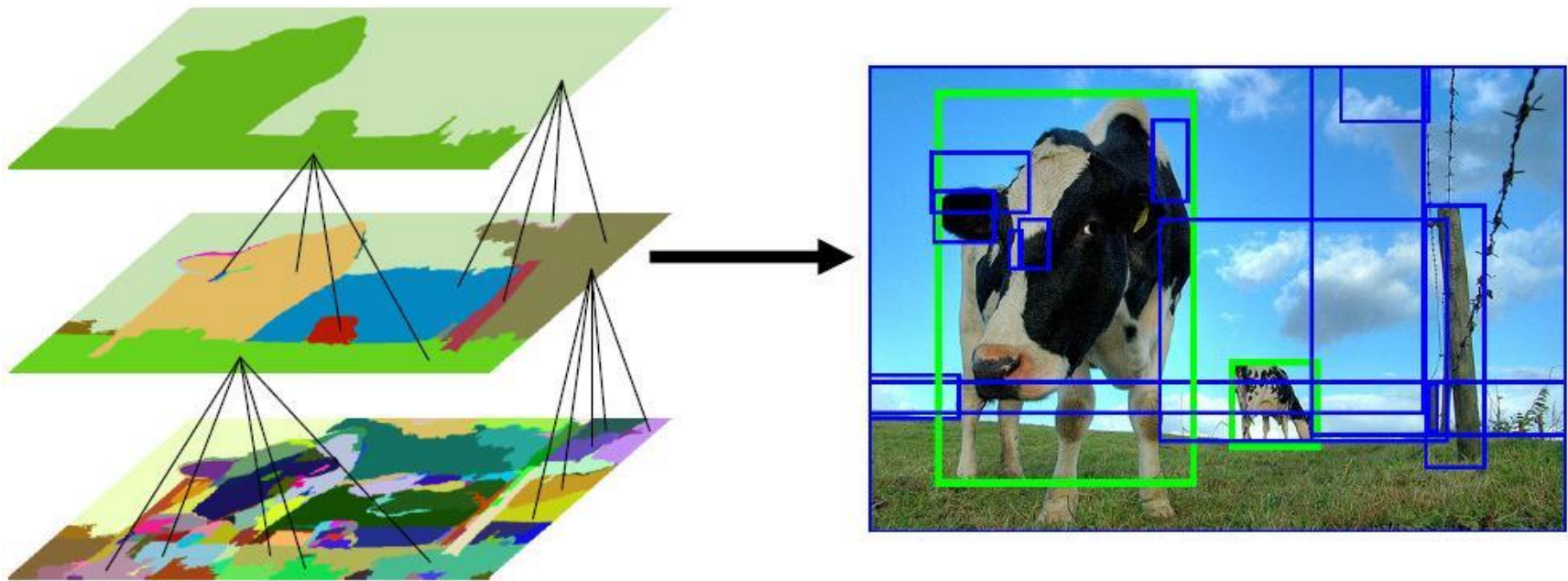
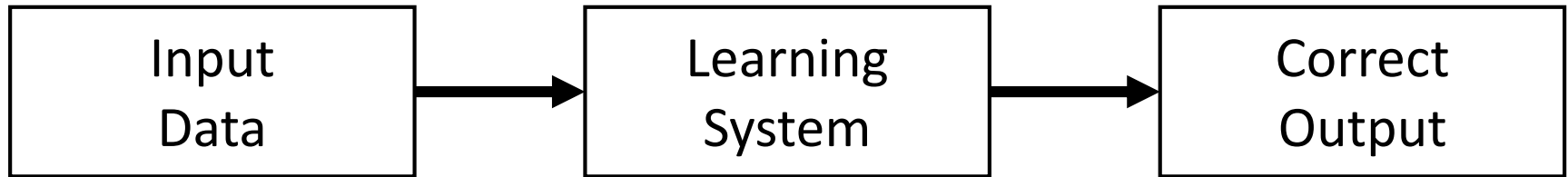
What can we do with Machine Learning?

Video Segmentation



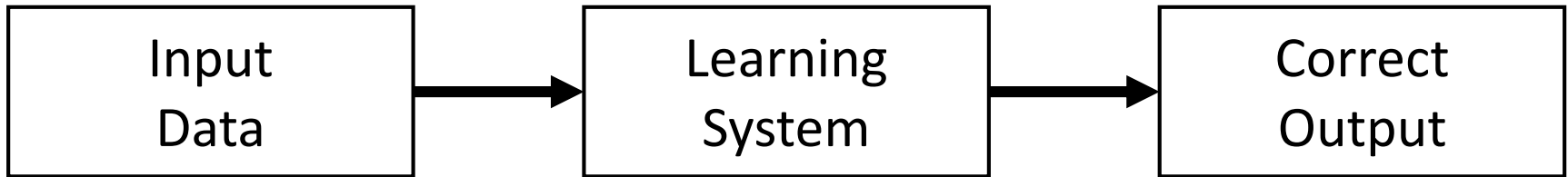
What can we do with Machine Learning?

Object Detection / Object Localization



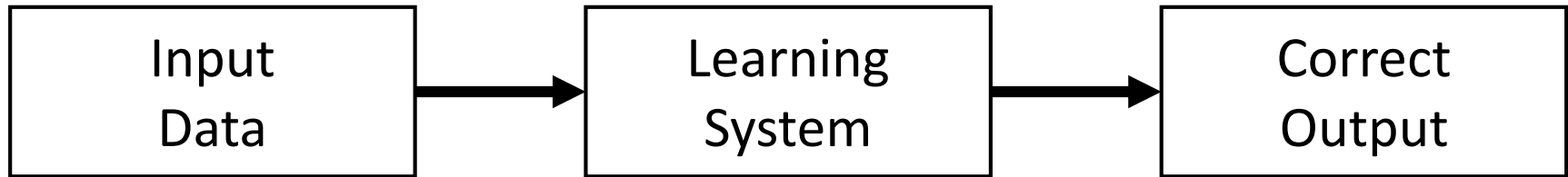
What can we do with Machine Learning?

Colorization of Images



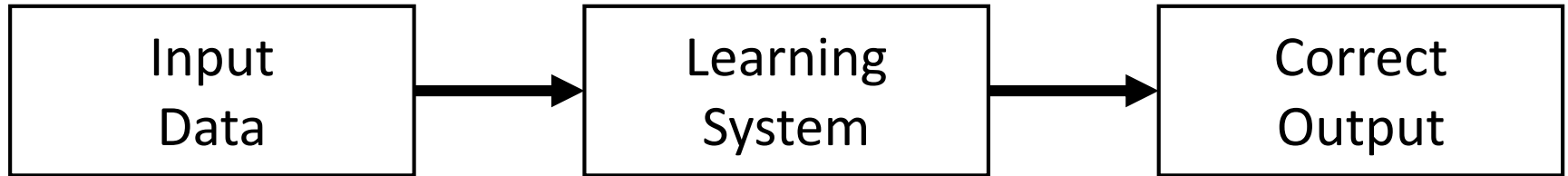
What can we do with Machine Learning?

Automatic Translation of Text in Images



What can we do with Machine Learning?

Handwriting Generation from Text



Text --- up to 100 characters, lower case letters work best

Global Business of Artificial Intelligence

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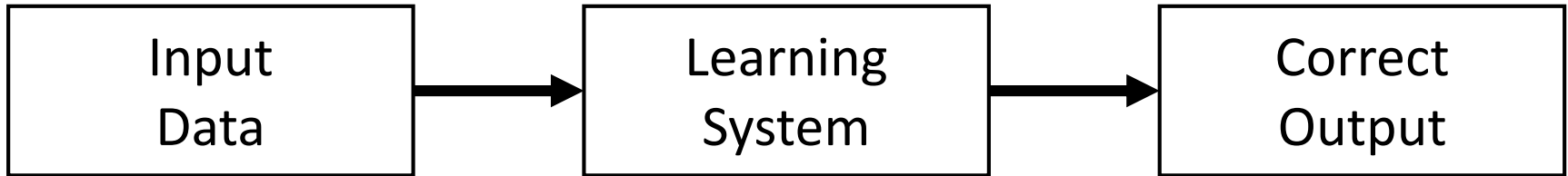
Global Business of Artificial Intelligence

Global Business of Artificial Intelligence

Global Business of Artificial Intelligence

What can we do with Machine Learning?

Character-Level Text Generation



Life Is About The Weather!

Life Is About The (Wild) Truth About Human-Rights

Life Is About The True Love Of Mr. Mom

Life Is About Where He Were Now

Life Is About Kids

Life Is About What It Takes If Being On The Spot Is Tough

Life Is About... An Eating Story

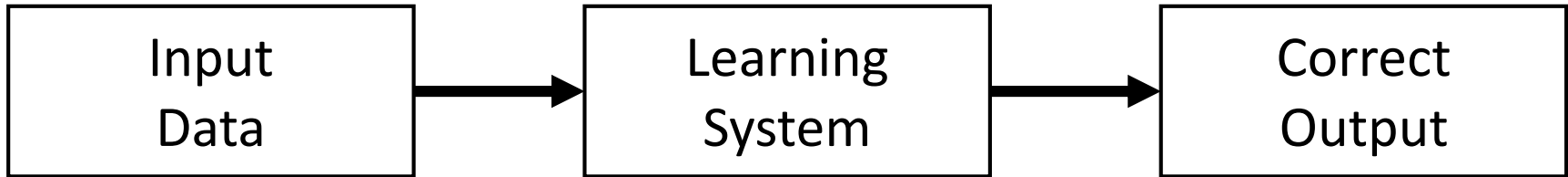
Life Is About The Truth Now

The meaning of life is literary recognition.

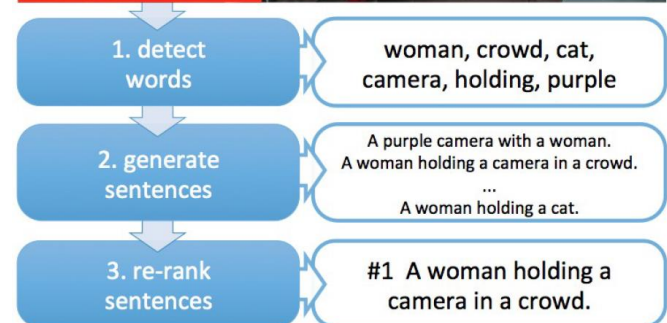
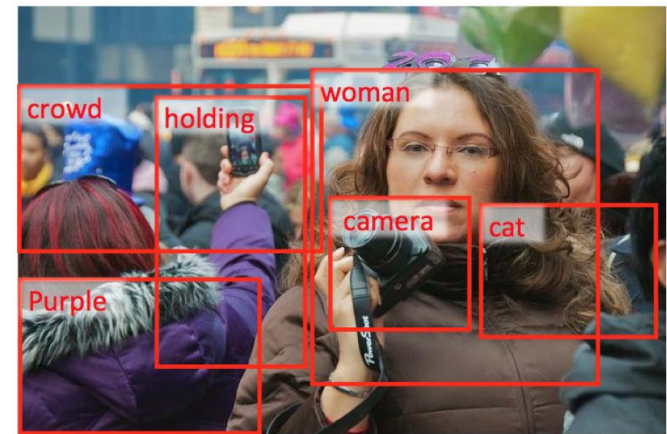
The meaning of life is the tradition of the ancient human reproduction

What can we do with Machine Learning?

Image Caption Generation

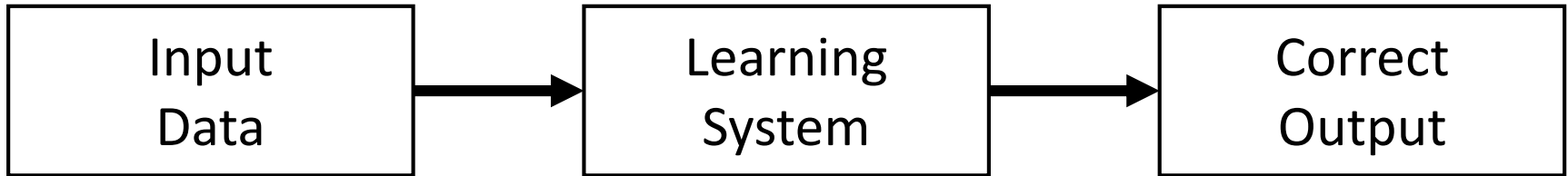


a man sitting on a couch with a dog
a man sitting on a chair with a dog in his lap

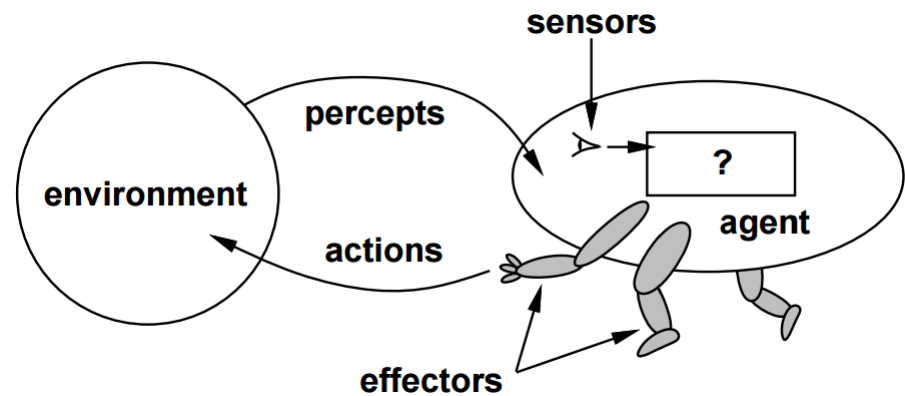
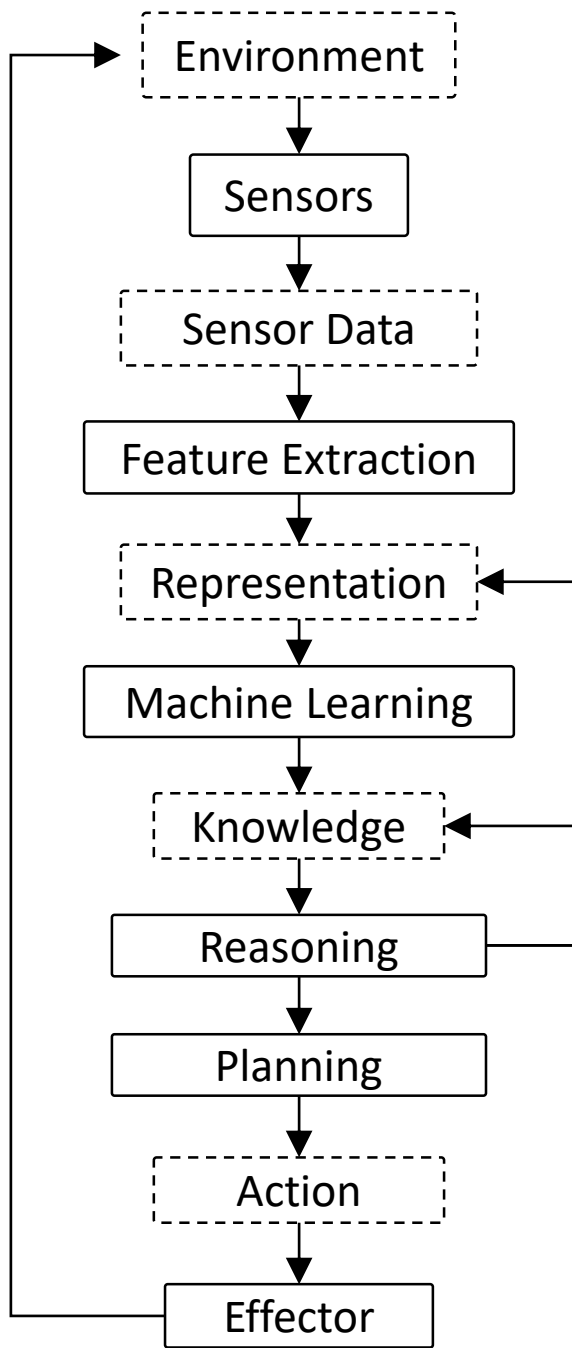


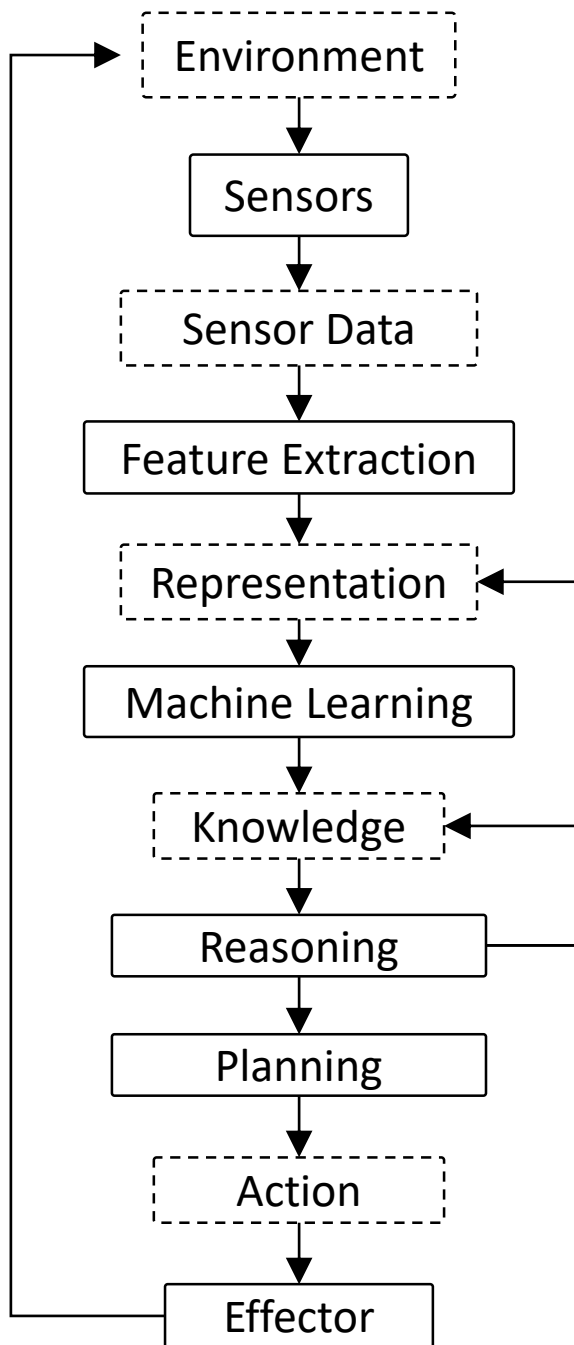
What can we do with Machine Learning?

End-to-End Learning of the Driving Task

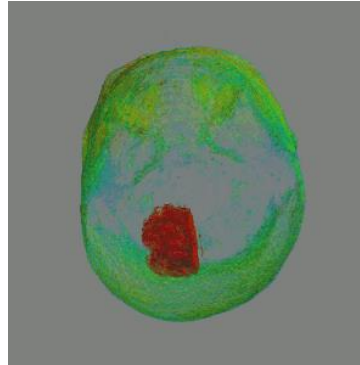


Open Question: What can we **not** do with Machine Learning?





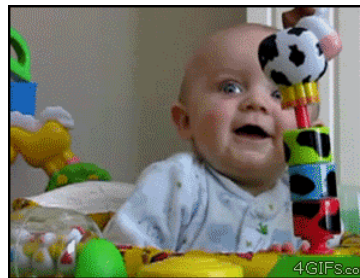
Formal tasks: Playing board games, card games. Solving puzzles, mathematical and logic problems.



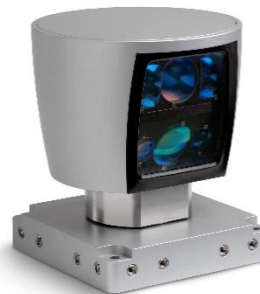
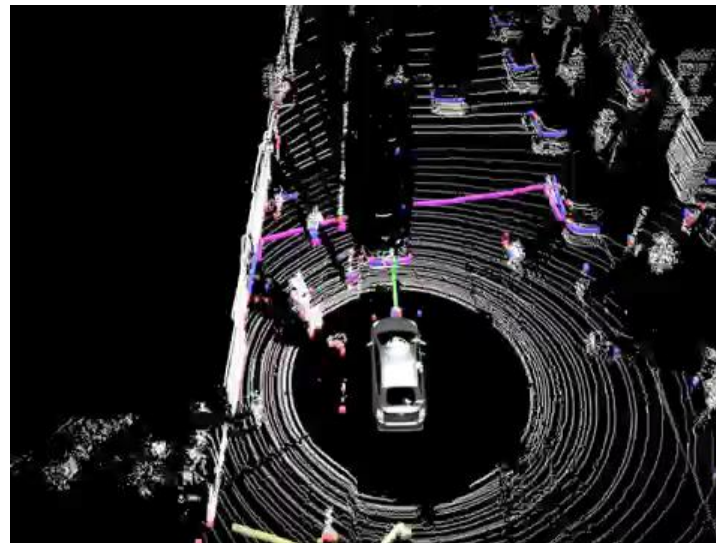
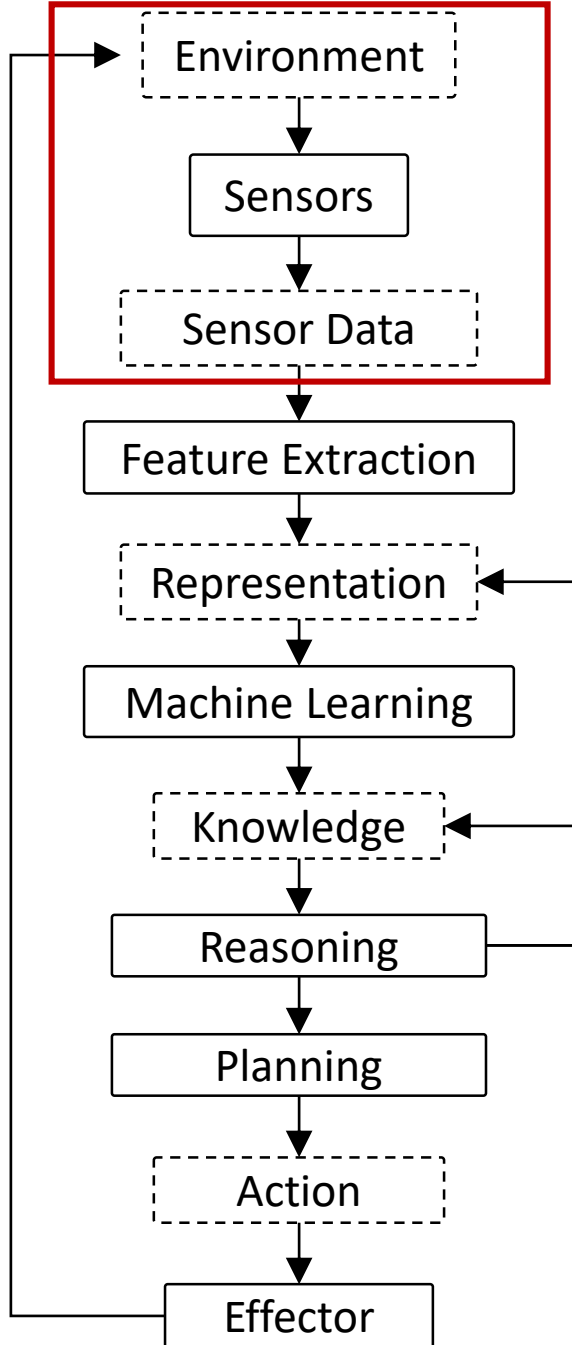
Expert tasks: Medical diagnosis, engineering, scheduling, computer hardware design.



Mundane tasks: Everyday speech, written language, perception, walking, object manipulation.



Human tasks: Awareness of self, emotion, imagination, morality, subjective experience, high-level-reasoning, consciousness.



Lidar



Camera
(Visible, Infrared)



Radar



GPS



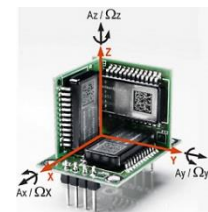
Stereo Camera



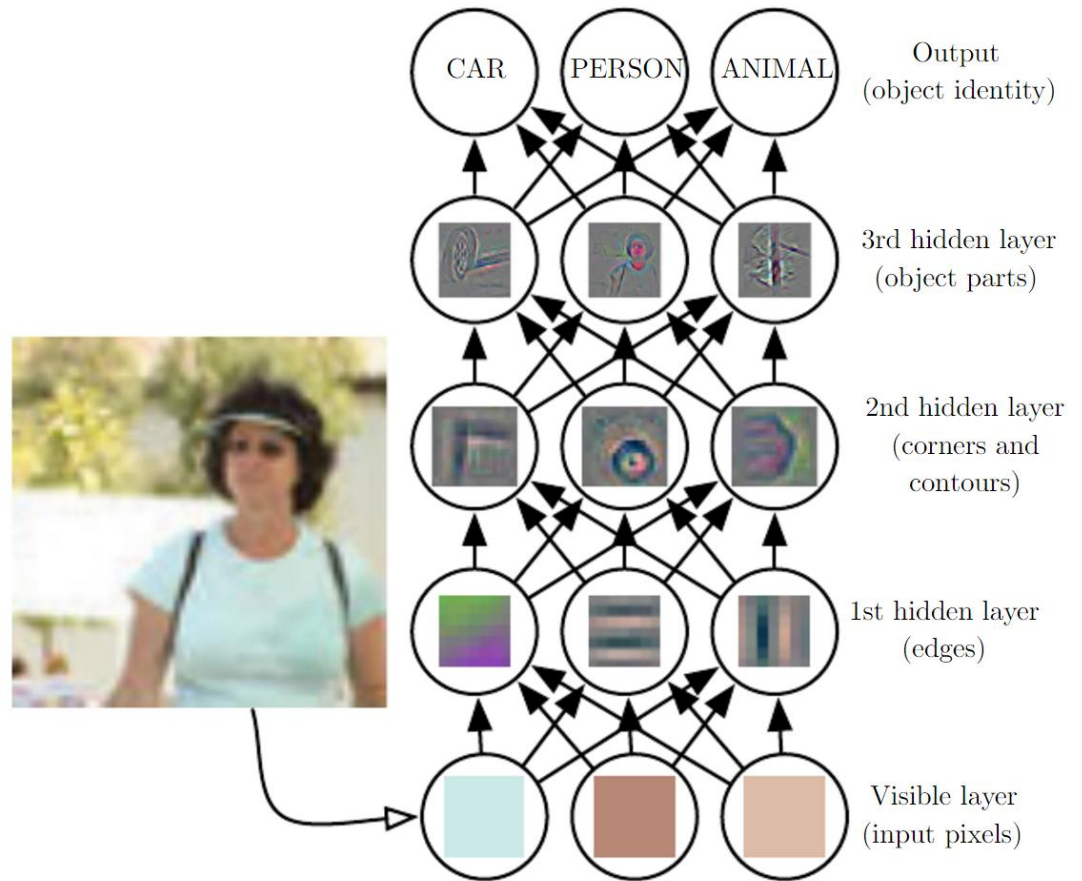
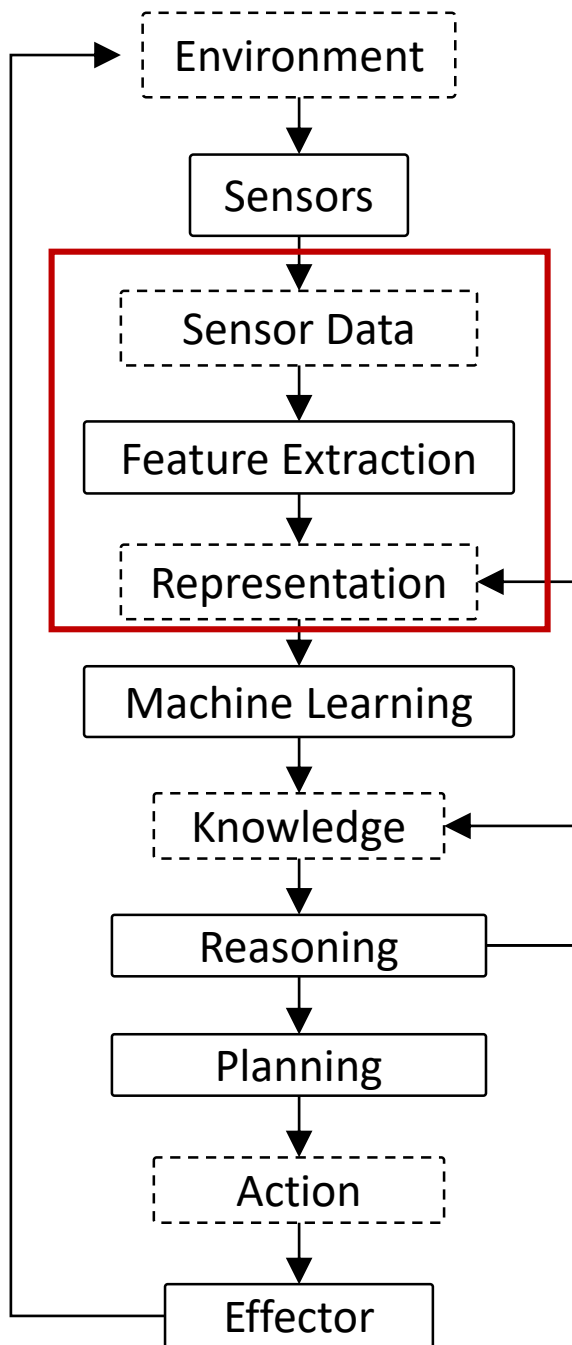
Microphone

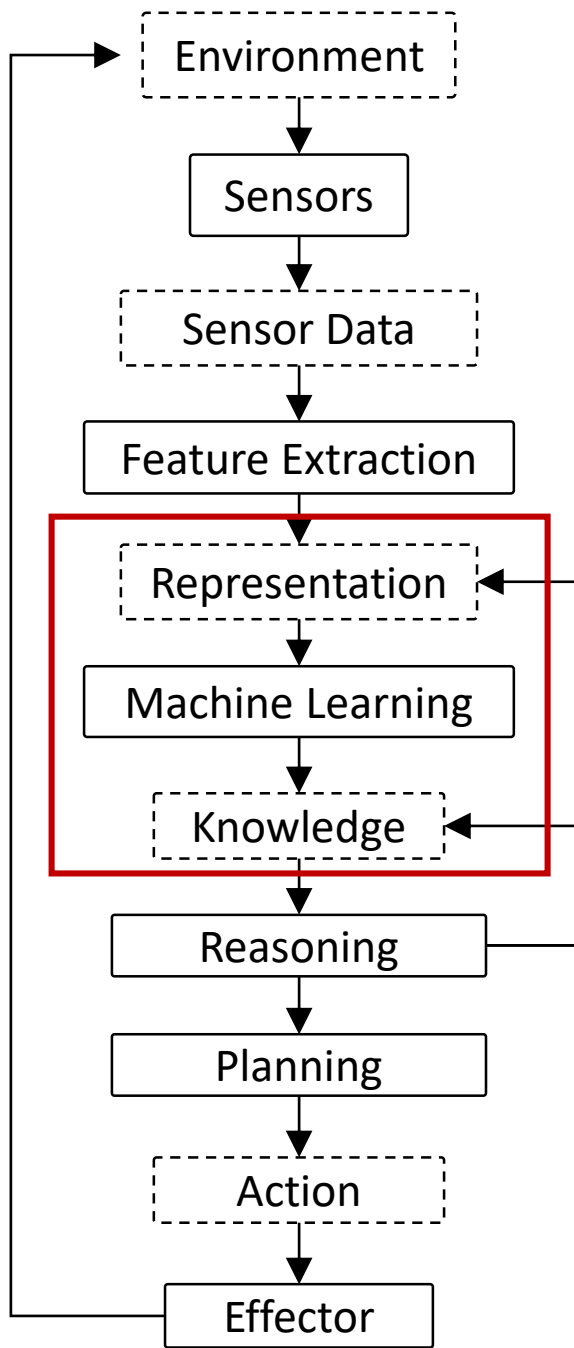


Networking
(Wired, Wireless)

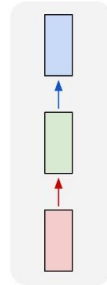


IMU

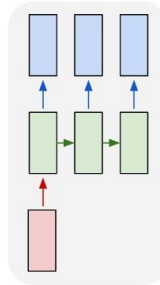




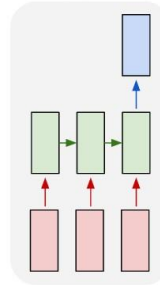
one to one



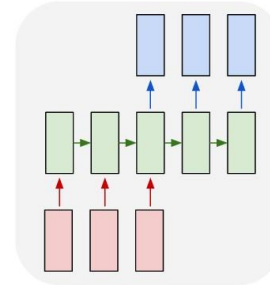
one to many



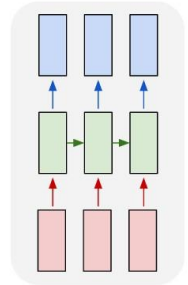
many to one



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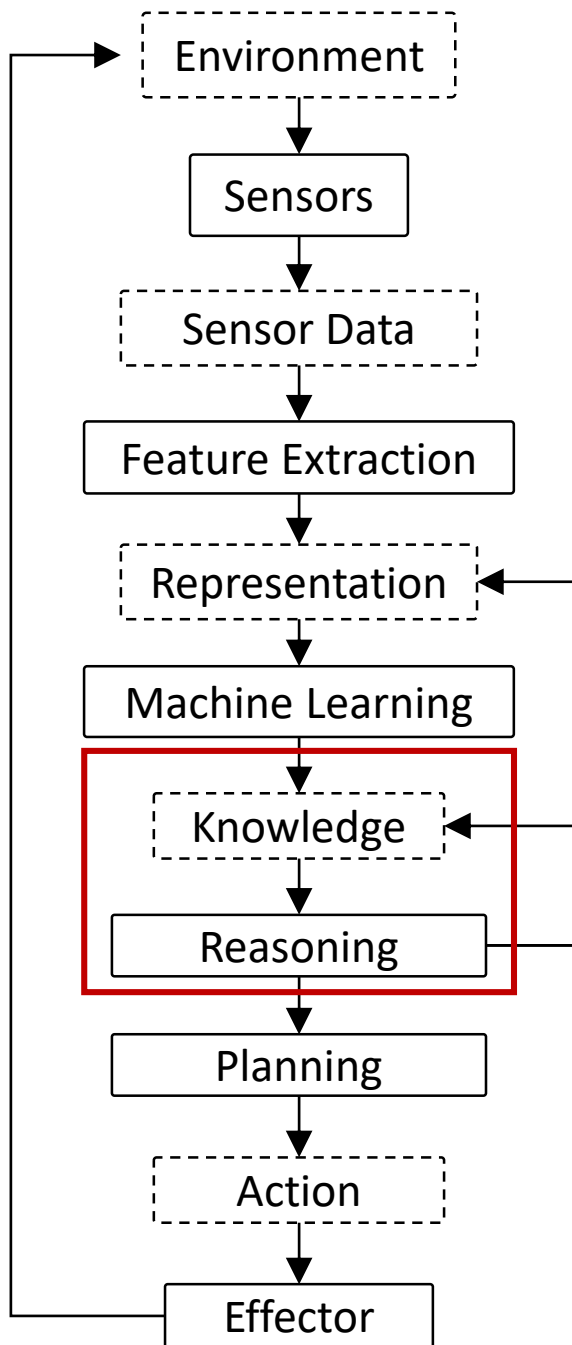


Image Recognition:
If it looks like a duck



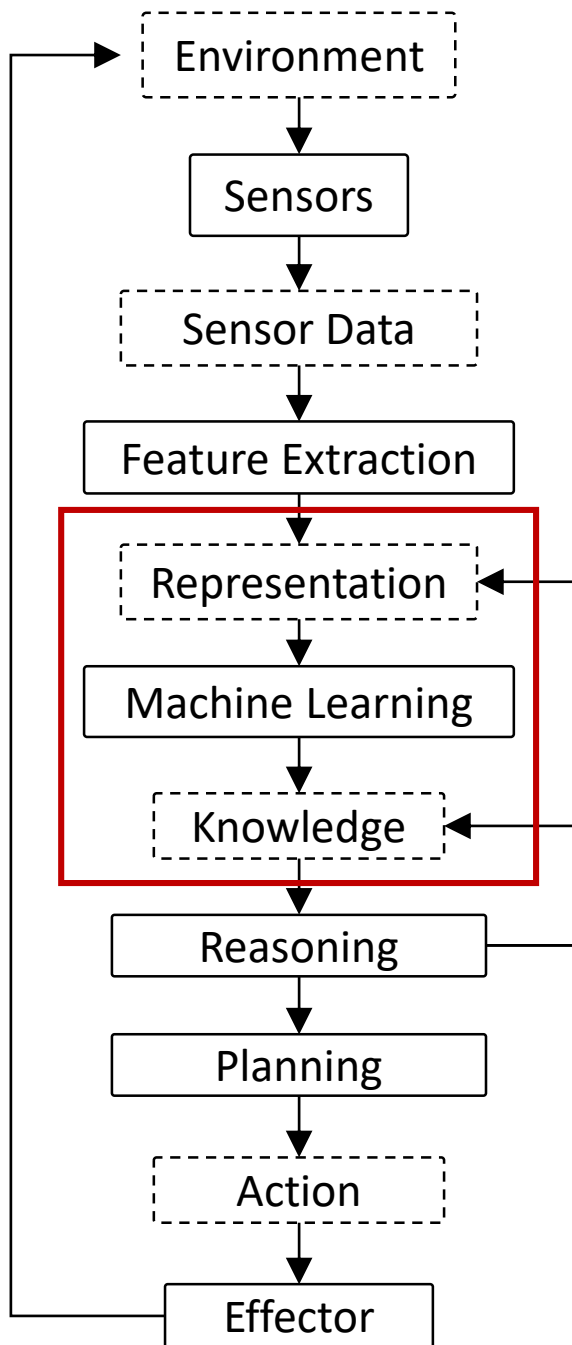
Audio Recognition:
Quacks like a duck



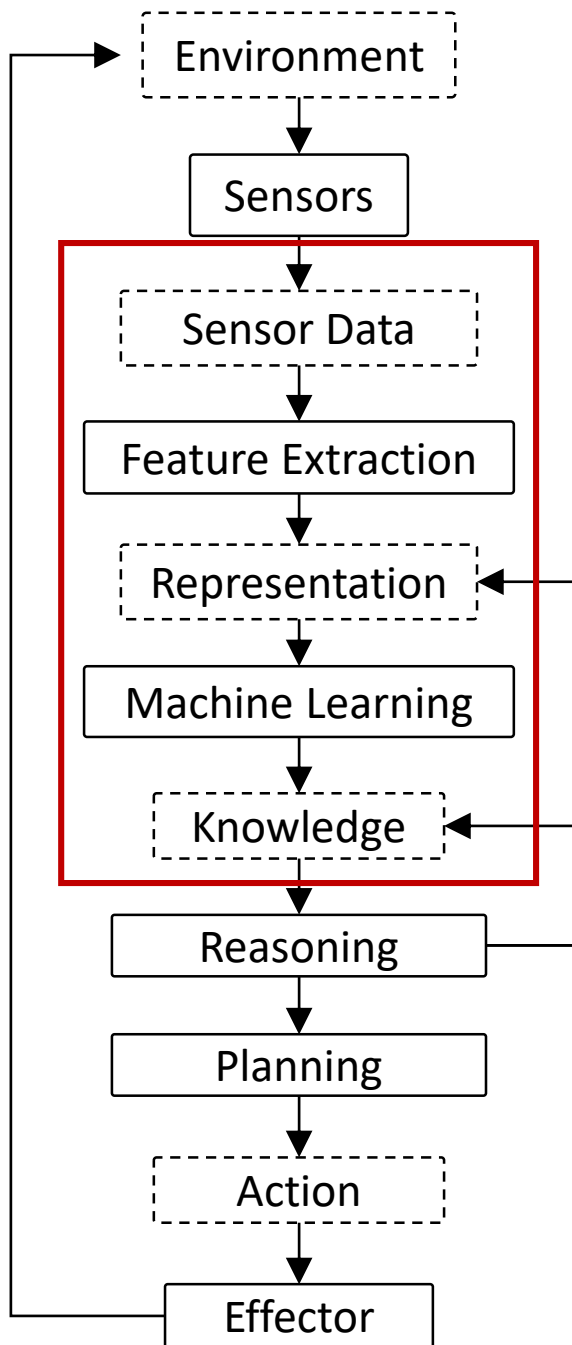
Activity Recognition:
Swims like a duck



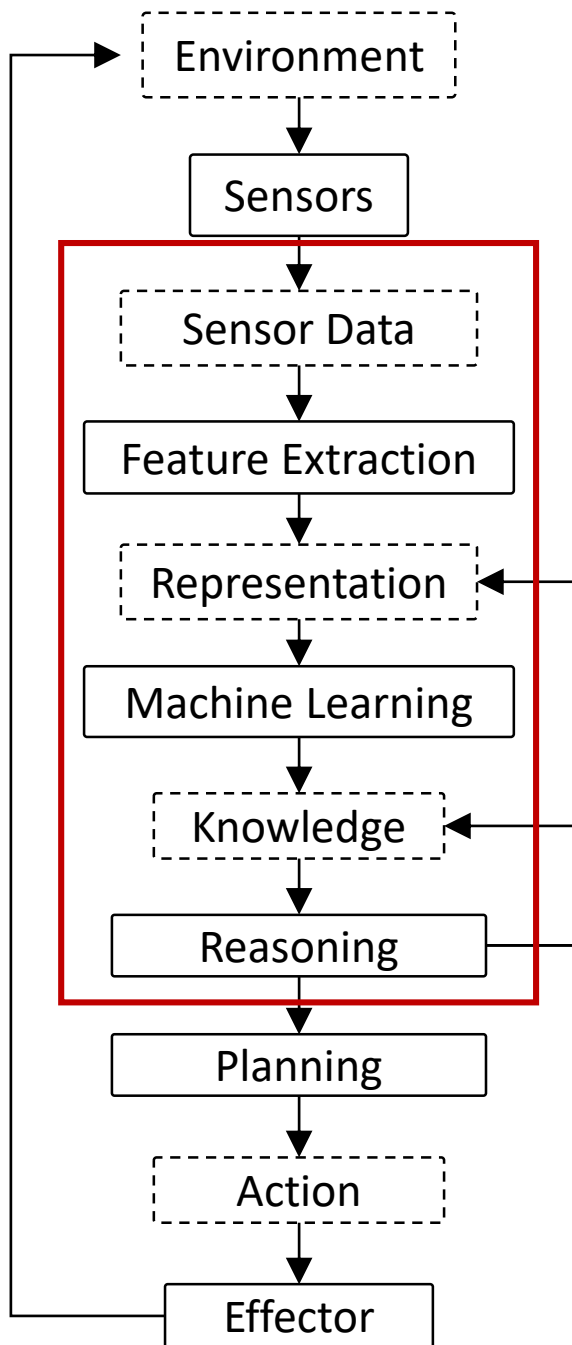
Open Question:
How much of this AI stack
can be **learned**?



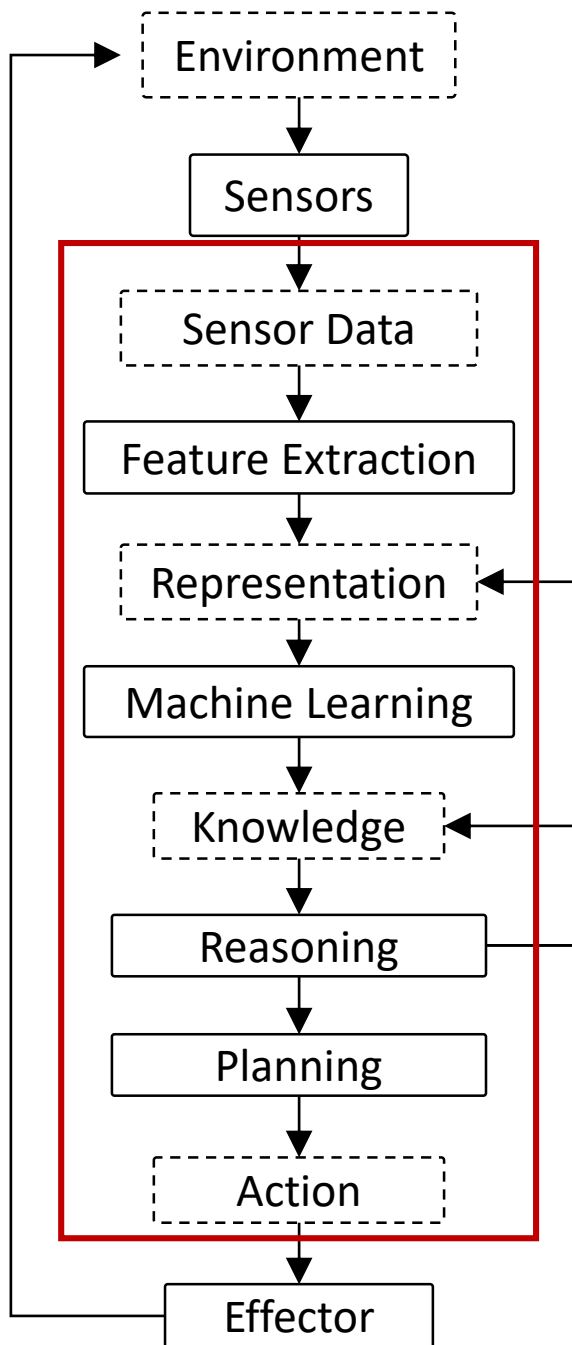
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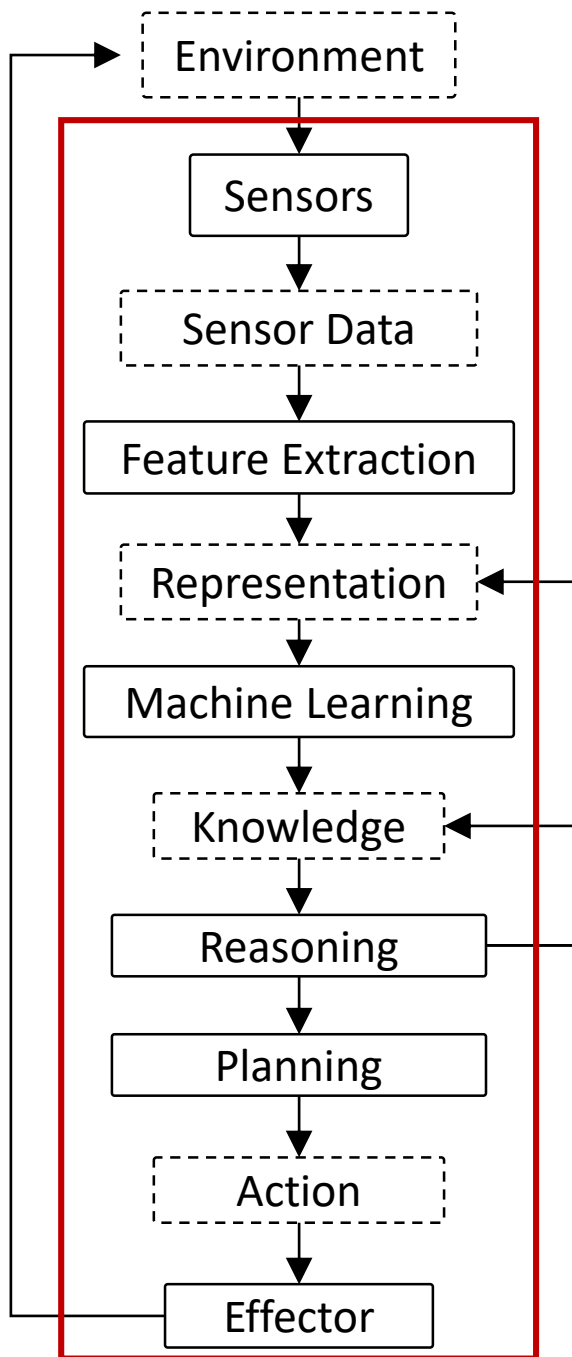
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you can make a product out of it. Otherwise, it’s still research.”

Question: Why?

Answer: Data

Visual perception: 540 millions years of data

Bipedal movement: 230+ million years of data

Abstract thought: 100 thousand years of data

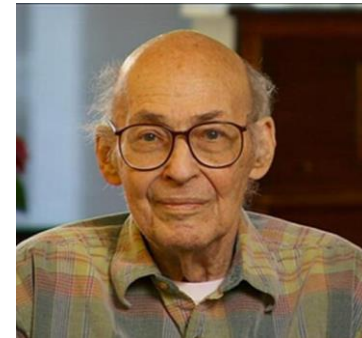
“Encoded in the large, highly evolved sensory and motor portions of the human brain is a **billion years of experience** about the nature of the world and how to survive in it.... Abstract thought, though, is a new trick, perhaps less than **100 thousand years** old. We have not yet mastered it. It is not all that intrinsically difficult; it just seems so when we do it.”
- *Hans Moravec, Mind Children (1988)*



Hans Moravec (CMU)



Rodney Brooks (MIT)



Marvin Minsky (MIT)

Moravec's Paradox: The “Easy” Problems are Hard



Soccer is harder than Chess





15.S14: Global Business of Artificial Intelligence (GBAIR)

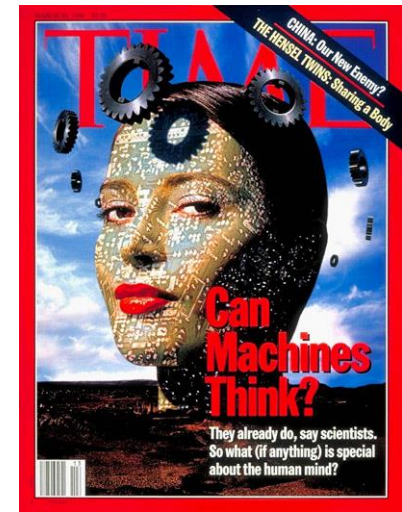
Machine Learning: The Promise, Limitations, and Mystery of Thinking Machines

(Part 2)

Guest Lecture: [Lex Fridman](#)



Artificial Intelligence Technology: Limited or Limitless?



Special Purpose:

Can it achieve a well-defined finite set of goals?

General Purpose:

Can it achieve poorly-defined unconstrained set of goals?



Today's Lecture:

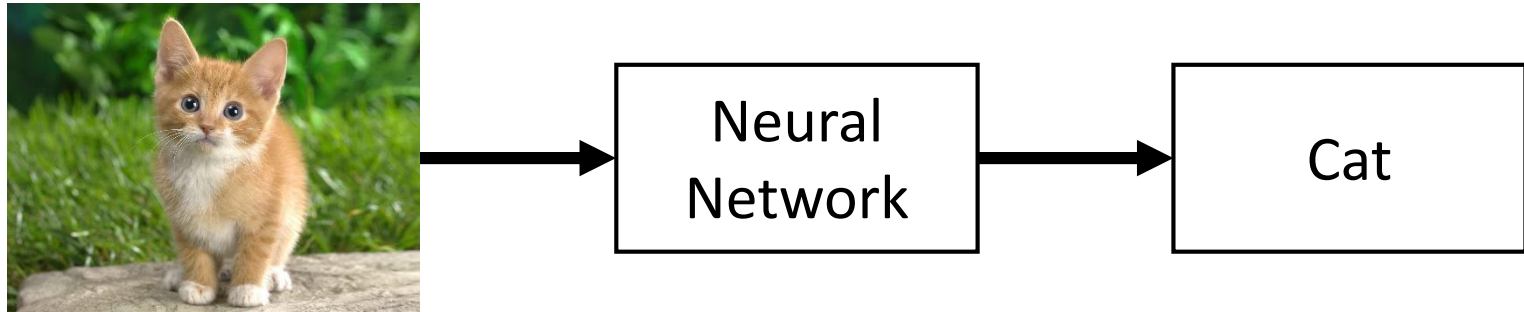
1. Overview current **approaches**
2. Highlight **limitations**
3. Discuss the **potential**
(and marvel at the mystery)

Best current answer:

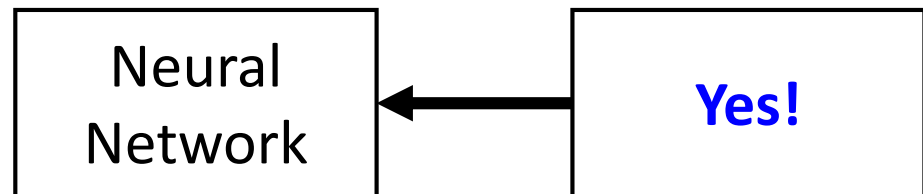
We Don't Know

How Neural Networks Learn: Backpropagation

Forward Pass:

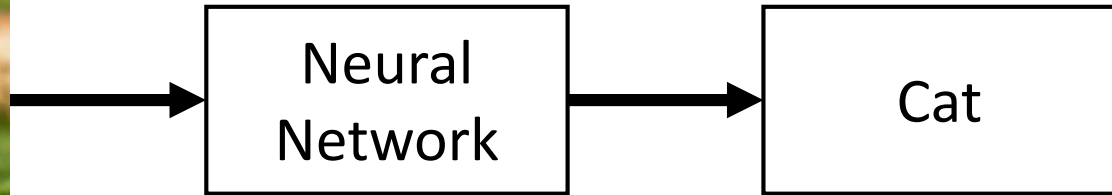
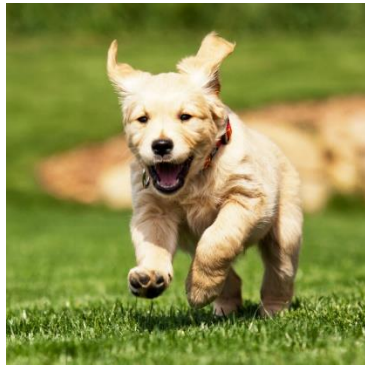


Backward Pass (aka Backpropagation):

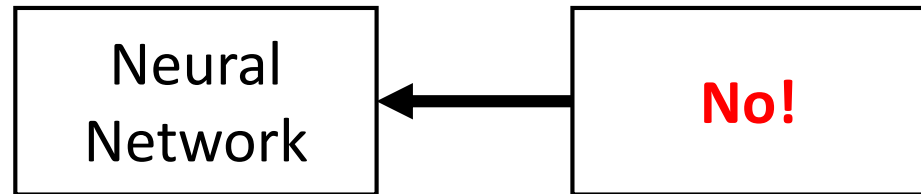


How Neural Networks Learn: Backpropagation

Forward Pass:

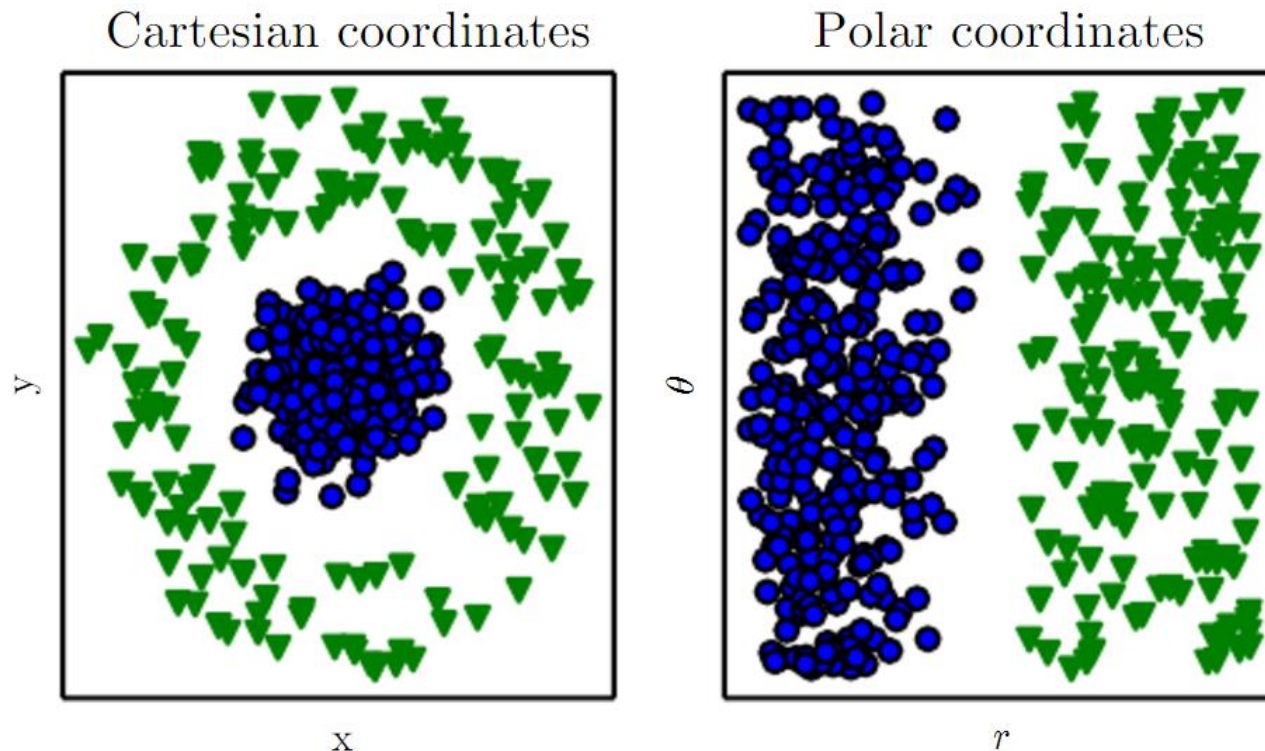
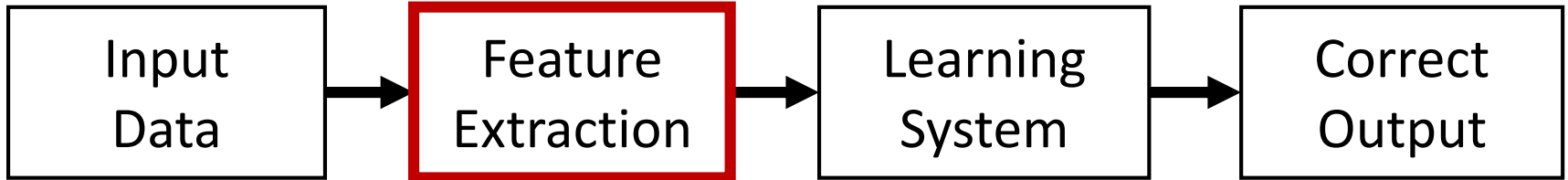


Backward Pass (aka Backpropagation):

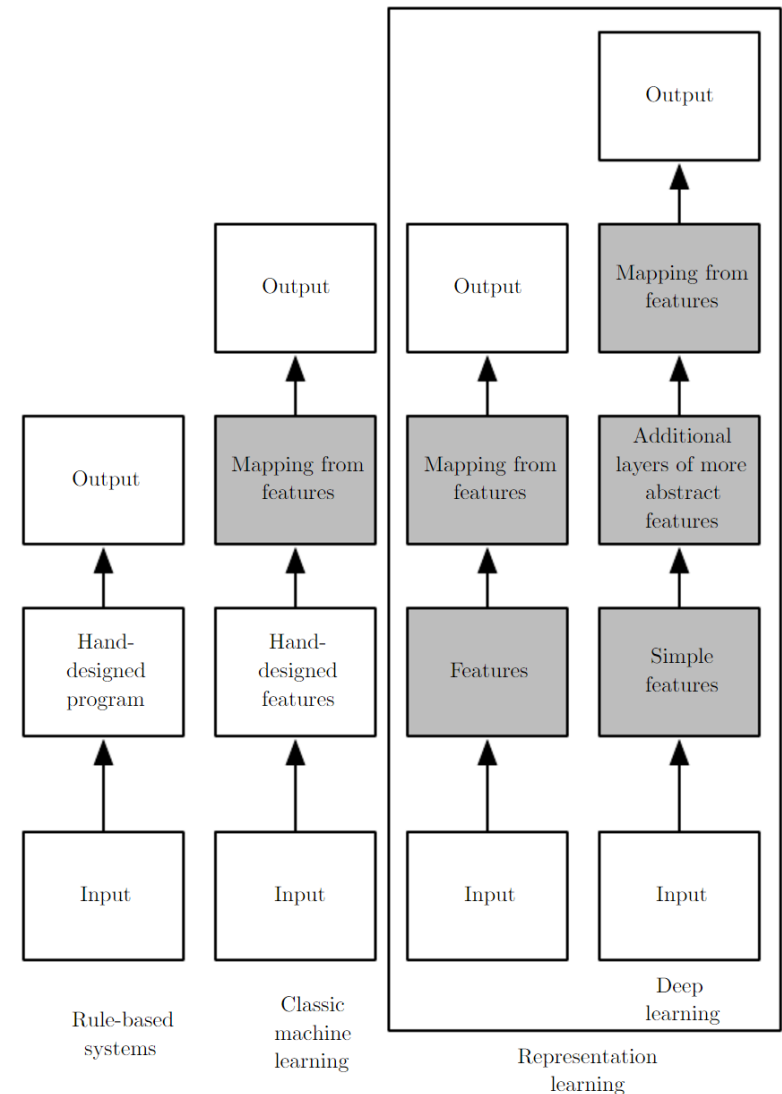
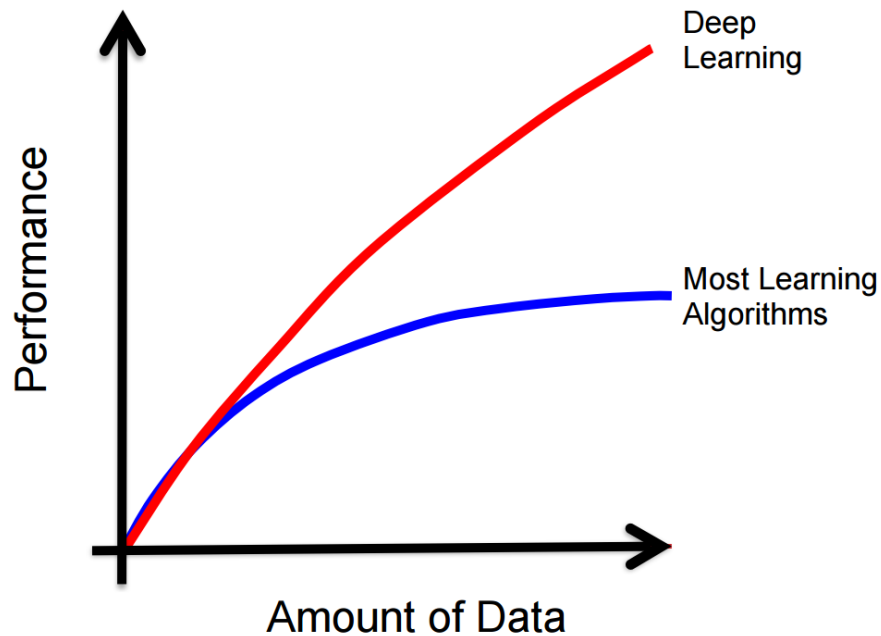


Representation Matters!

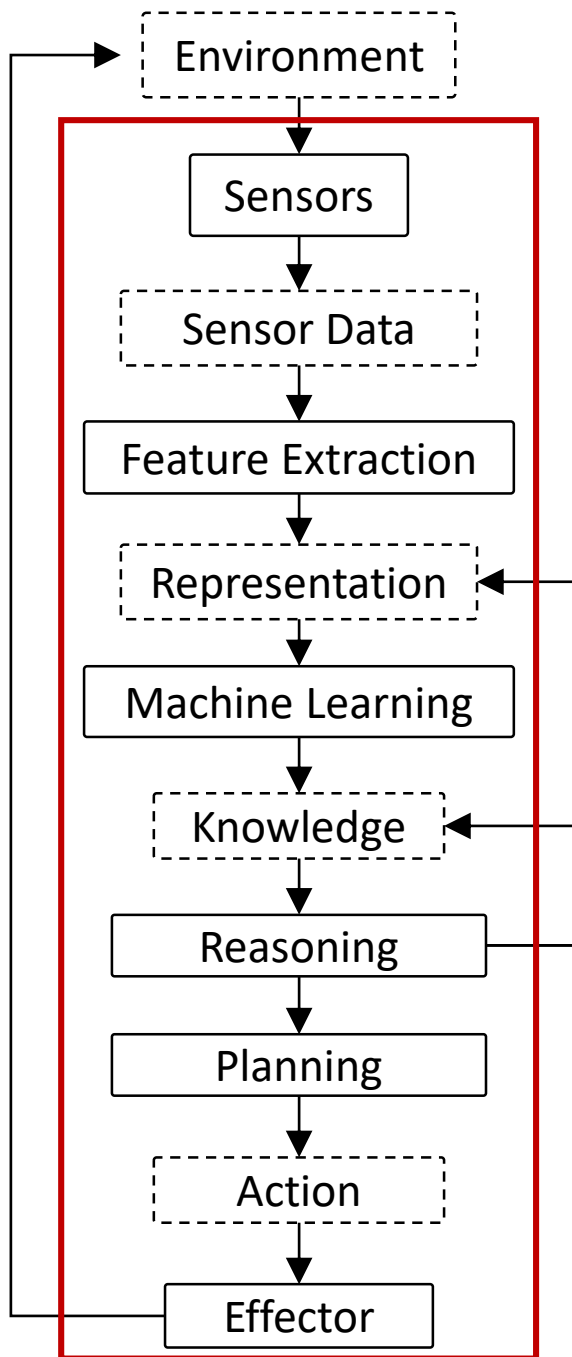
(Representation aka Features)



Deep Learning: **Scalable** Machine Learning



Open Question:
How much of this AI stack
can be **learned**?



Question: Why?

Answer: Data

Visual perception: 540 millions years of data

Bipedal movement: 230+ million years of data

Abstract thought: 100 thousand years of data

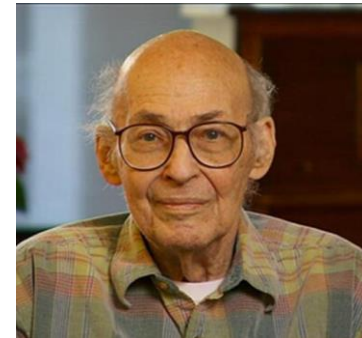
“Encoded in the large, highly evolved sensory and motor portions of the human brain is a **billion years of experience** about the nature of the world and how to survive in it.... Abstract thought, though, is a new trick, perhaps less than **100 thousand years** old. We have not yet mastered it. It is not all that intrinsically difficult; it just seems so when we do it.”
- *Hans Moravec, Mind Children (1988)*



Hans Moravec (CMU)

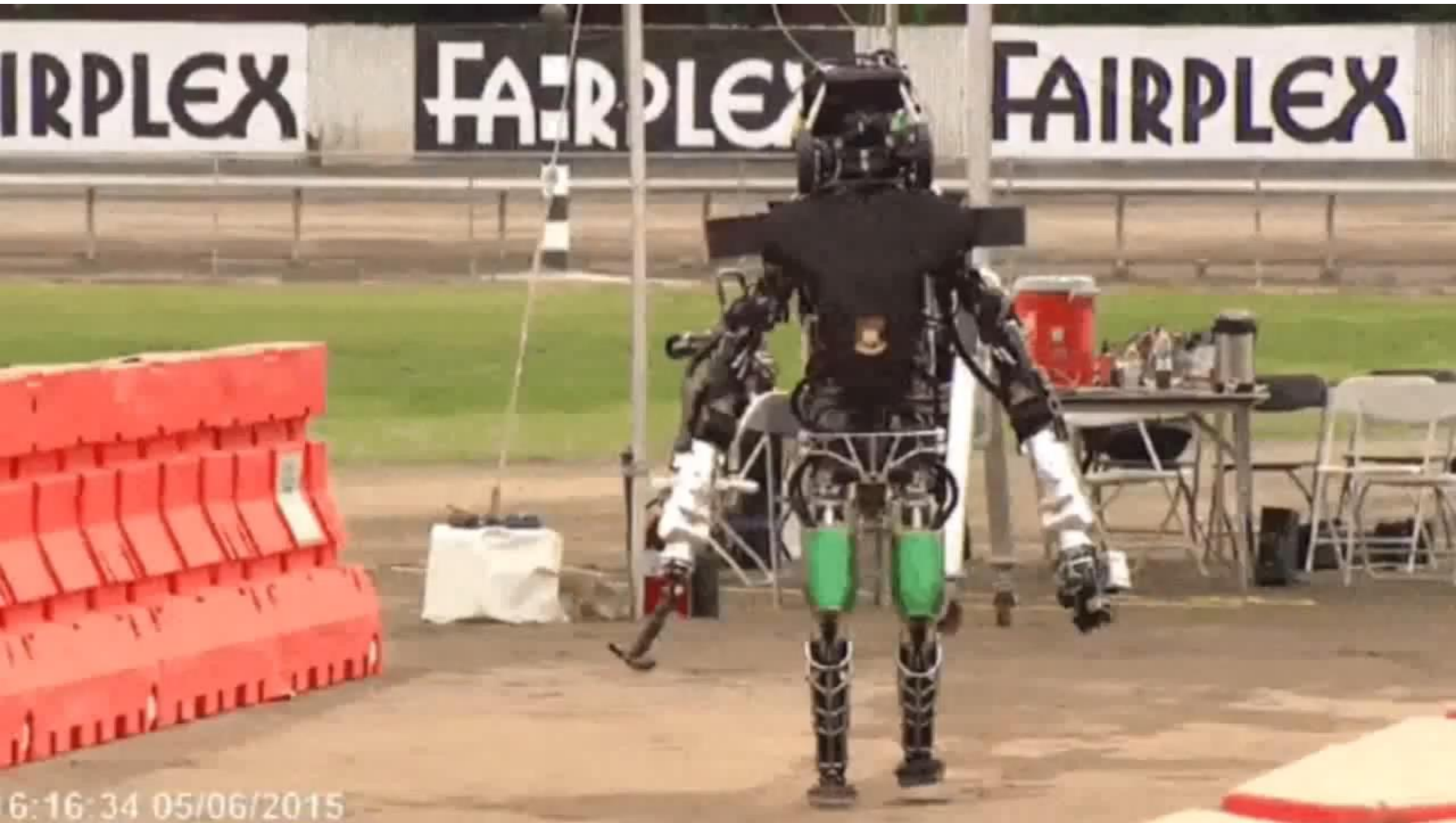


Rodney Brooks (MIT)



Marvin Minsky (MIT)

Moravec's Paradox: The “Easy” Problems are Hard



Challenge and Opportunity:

Real World Application

(Robustness)

Computer Vision for Intelligent Systems

3D Scene



Feature
Extraction

Texture

Color

Optical
Flow

Stereo
Disparity

Grouping

Surfaces

Bits of
objects

Sense of
depth

Motion
patterns

Interpretation

Objects

Agents
and goals

Shapes and
properties

Open
paths

Words

Action

Walk, touch, contemplate, smile, evade, read on, pick up, ...

Images are Numbers



08	02	22	97	38	15	00	40	00	75	04	05	07	78	52	12	50	77	81	28
49	49	99	40	17	81	18	57	60	87	17	40	98	43	69	48	04	56	62	00
81	49	31	73	55	79	14	29	93	71	40	67	52	88	30	03	49	13	36	65
52	70	95	23	04	60	11	42	69	24	68	56	01	32	56	71	37	02	36	91
22	31	16	71	51	63	83	59	41	92	36	54	22	40	40	28	66	33	13	80
24	47	33	60	99	03	45	02	44	75	33	53	78	36	84	20	35	17	12	50
32	98	81	28	64	23	67	10	26	38	40	67	59	54	70	66	18	38	64	70
67	26	20	68	02	62	12	20	95	63	94	39	63	08	40	91	66	49	94	21
24	55	58	05	66	73	99	26	97	17	78	78	96	83	14	88	34	89	63	72
21	36	23	09	75	00	76	44	20	45	35	14	00	61	33	97	34	31	33	95
78	17	53	28	22	75	31	67	15	94	03	80	04	62	16	14	09	53	56	92
16	39	05	42	96	35	31	47	55	58	88	24	00	17	54	24	36	29	85	57
86	56	00	48	35	71	89	07	05	44	44	37	44	60	21	58	51	54	17	58
19	80	81	68	05	94	47	69	28	73	92	13	86	52	17	77	04	89	55	40
04	52	08	83	97	35	99	16	07	97	57	32	16	26	26	79	33	27	98	66
55	46	68	87	57	62	20	72	03	46	33	67	46	55	12	32	63	93	53	69
04	42	16	73	35	35	39	11	24	94	72	18	08	46	29	32	40	62	76	36
20	69	36	41	72	30	23	88	34	65	99	69	82	67	59	85	74	04	36	16
20	73	35	29	78	31	90	01	74	31	49	71	48	56	31	16	23	57	05	54
01	70	54	71	83	51	54	69	16	92	33	48	61	43	52	01	89	23	63	48

What the computer sees

image classification

82% cat
15% dog
2% hat
1% mug

Computer Vision is Hard

Viewpoint variation



Scale variation



Deformation



Occlusion



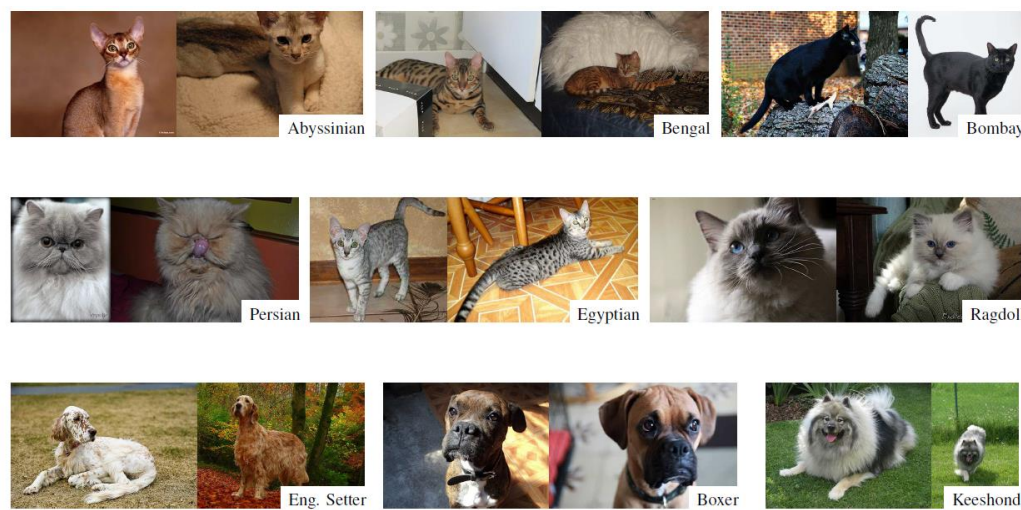
Illumination conditions



Background clutter



Intra-class variation



Object Classification Challenge: Occlusion



Object Classification Challenge: Occlusion



Object Classification Challenge: Occlusion



Object Classification Challenge: Occlusion



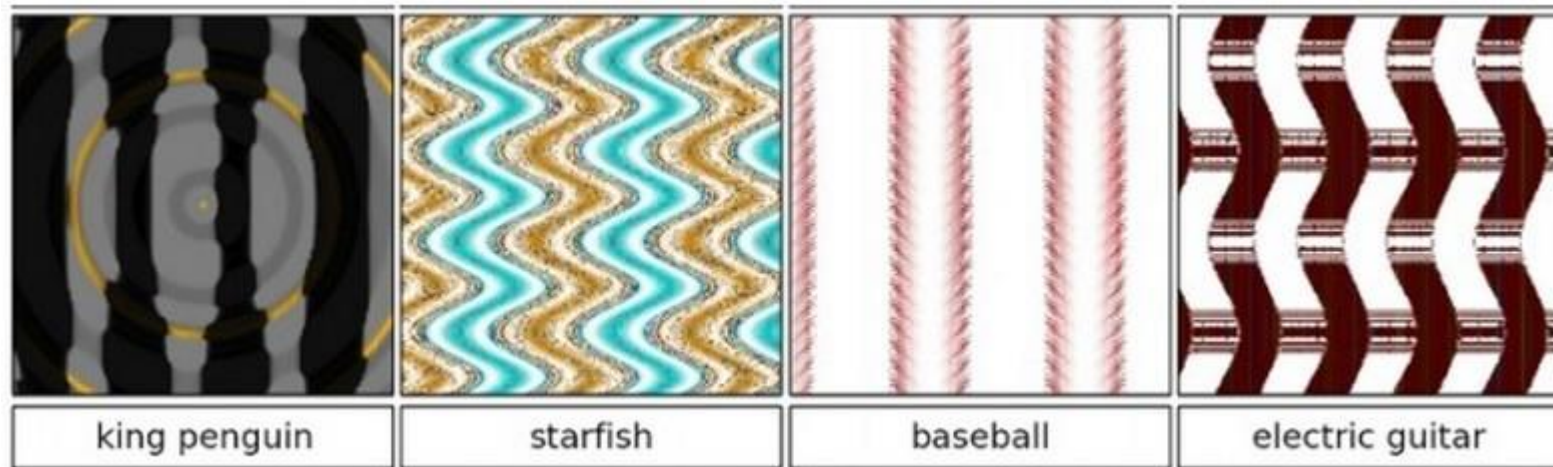
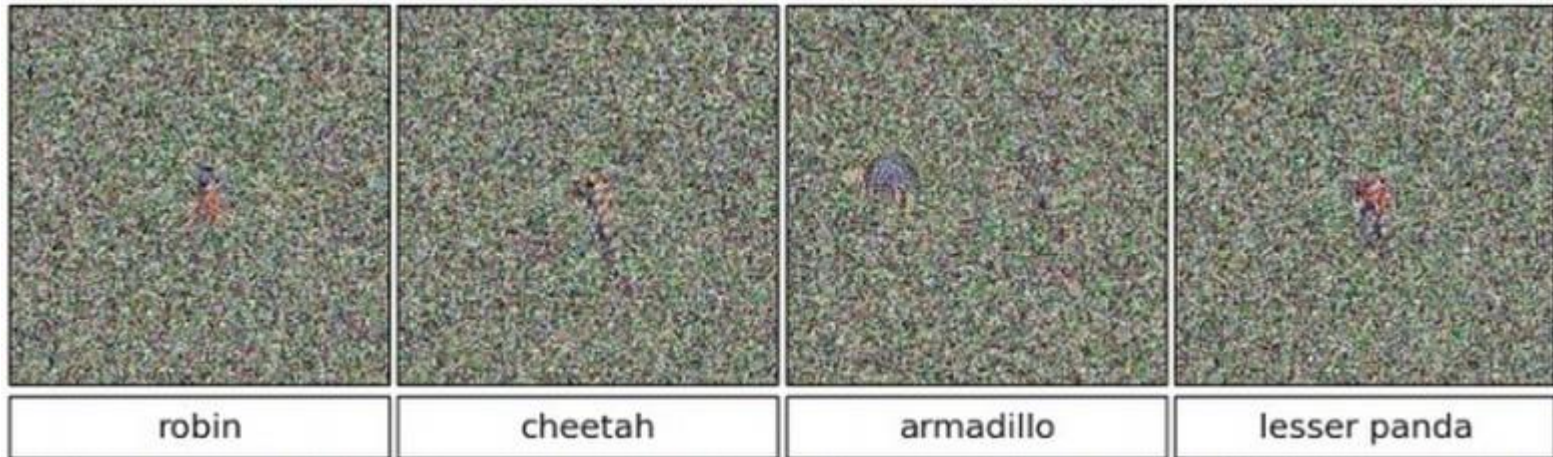
Object Classification Challenge: Occlusion



10
Cats

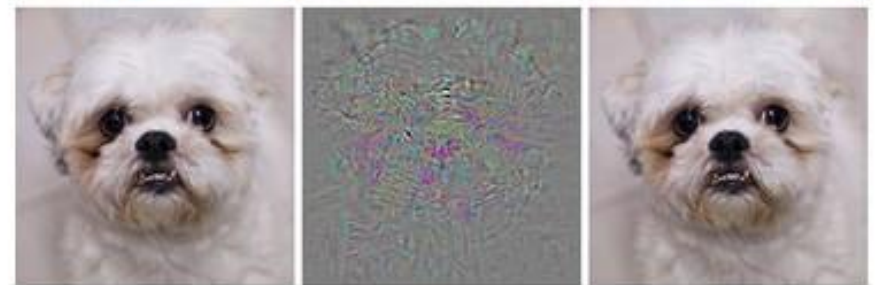
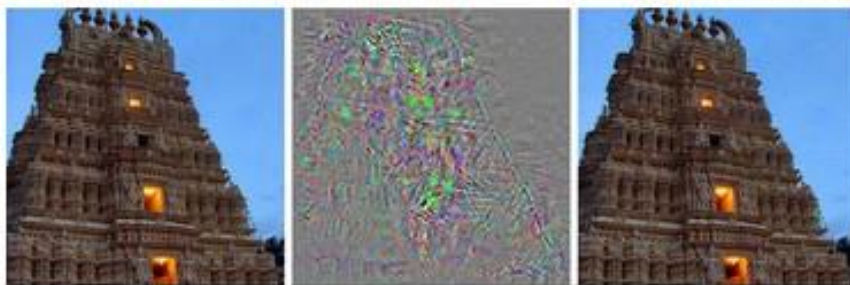
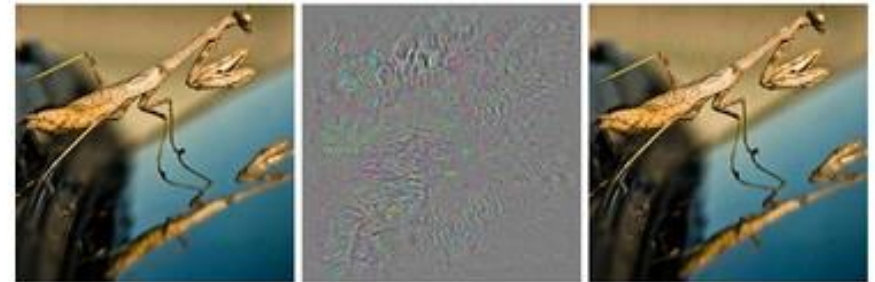
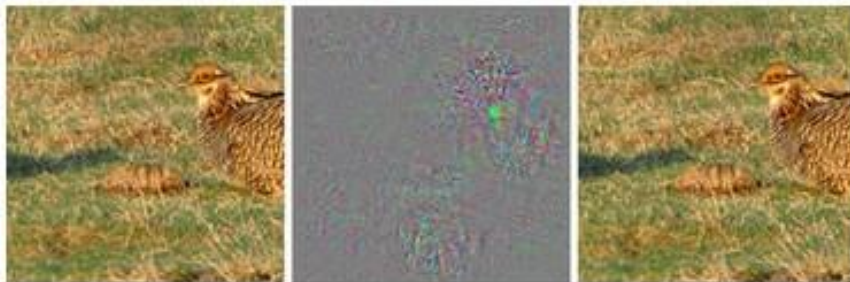
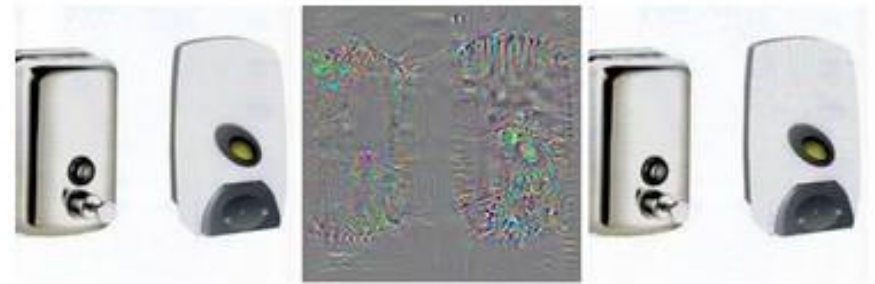
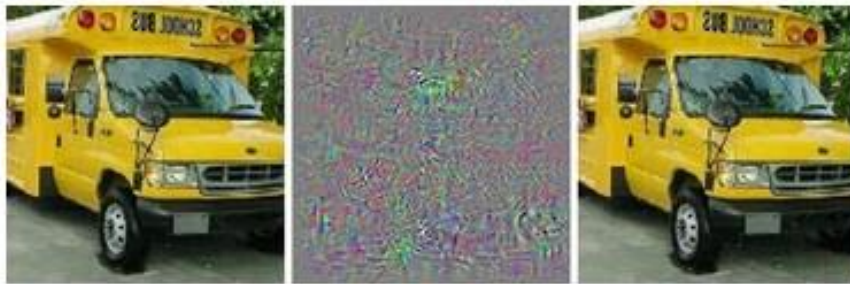
Robustness:

>99.6% Confidence in the Wrong Answer



Nguyen et al. "Deep neural networks are easily fooled: High confidence predictions for unrecognizable images." 2015.

Robustness: Fooled by a Little Distortion



correct

+distort

ostrich

correct

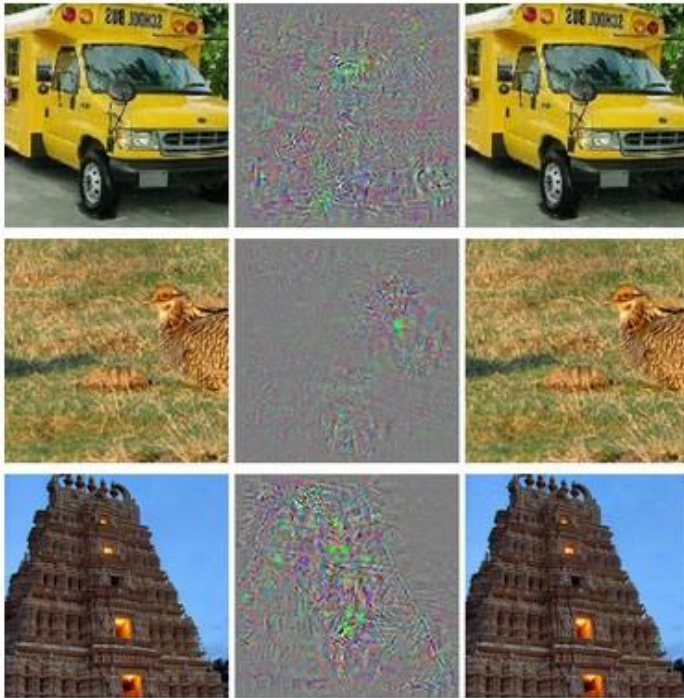
+distort

ostrich

Szegedy et al. "Intriguing properties of neural networks." 2013.

Sensor Spoofing

Camera Spoofing



correct

+distort

ostrich

LIDAR Spoofing



Challenge and Opportunity:

Sparsely-Labeled Data

Current Challenges

- **Lacks Reasoning:**

Unable to build unconstrained knowledge graphs from small human-defined seed graphs

- **Inefficient Learners:**

Every “concept” needs a lot of examples

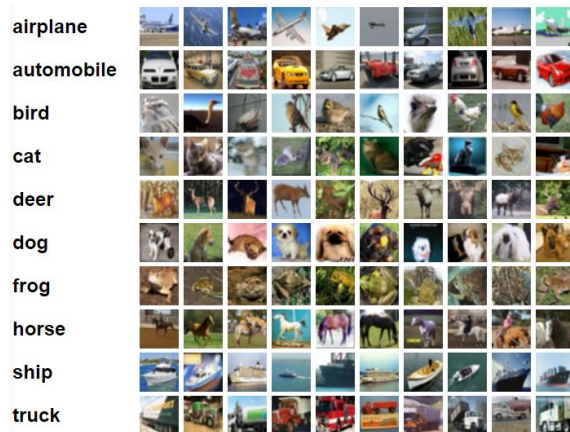
- **Label Cost:**

Supervised data is costly

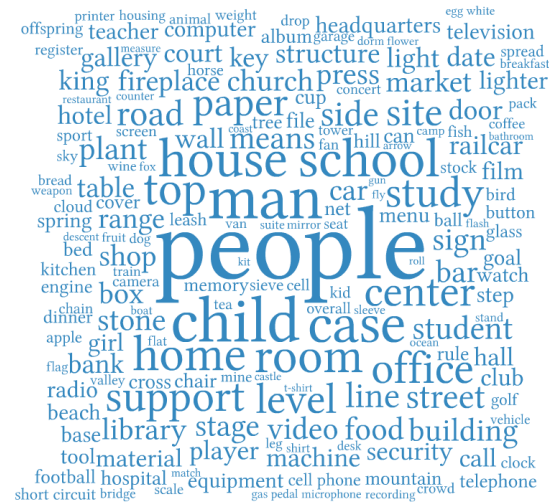
Supervised Data Example: Computer Vision Datasets



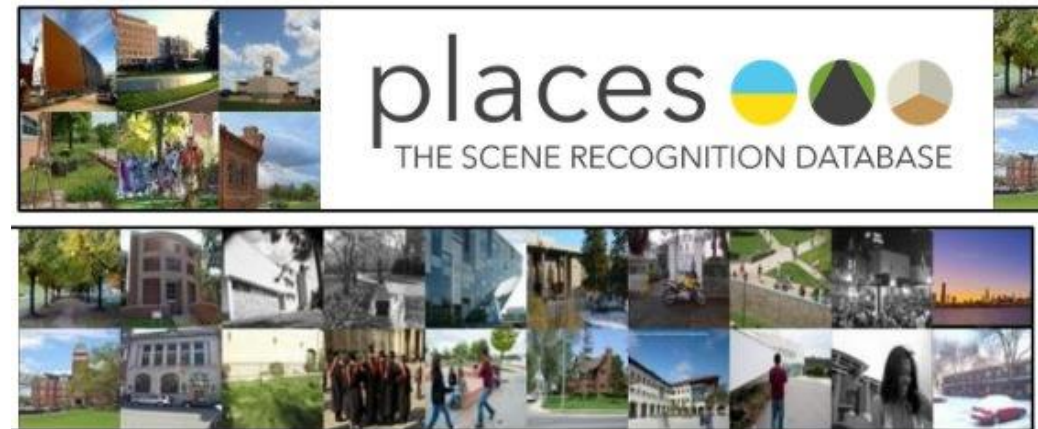
MNIST: handwritten digits



CIFAR-10(0): tiny images



ImageNet: WordNet hierarchy

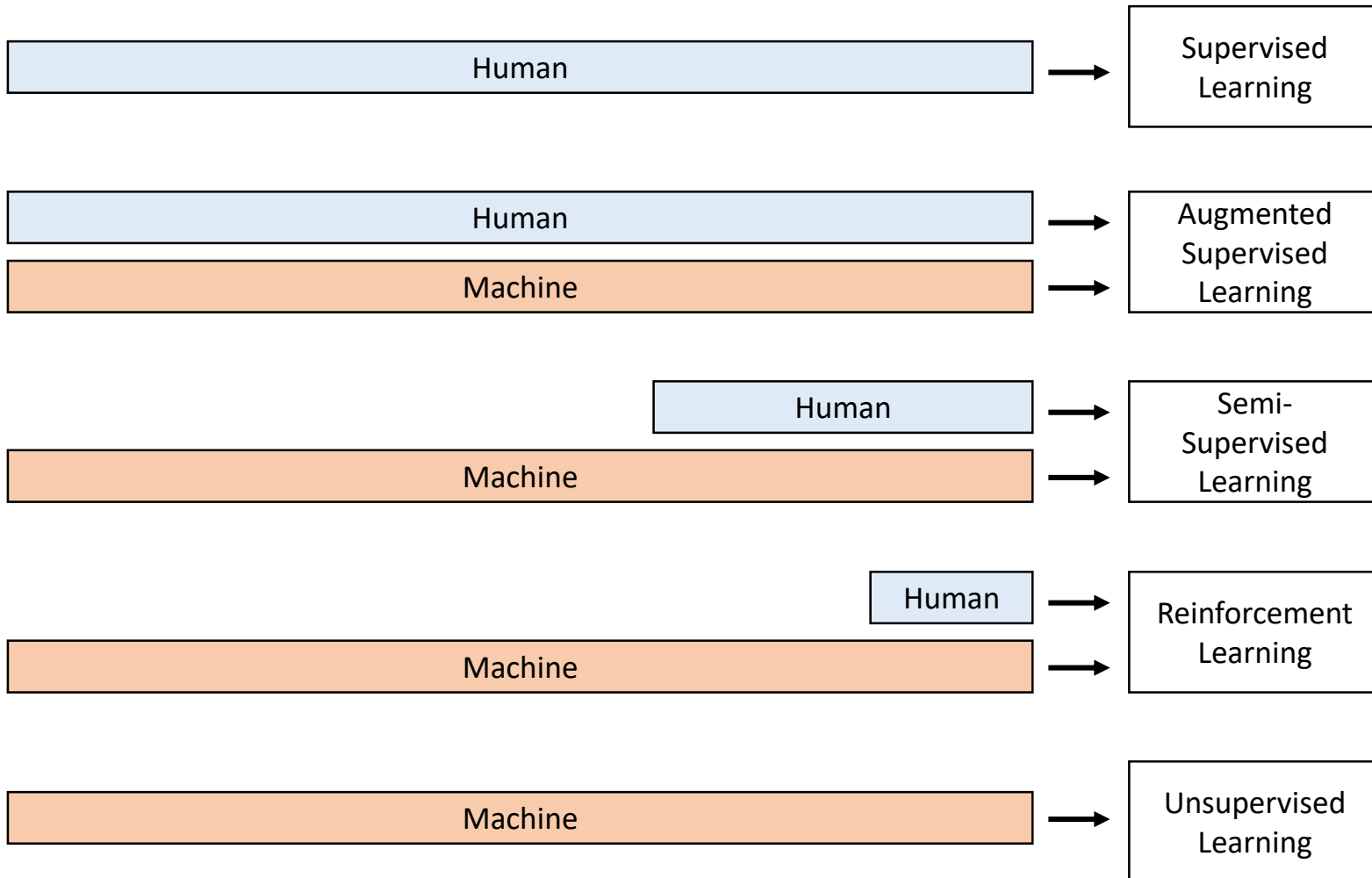


Places: natural scenes

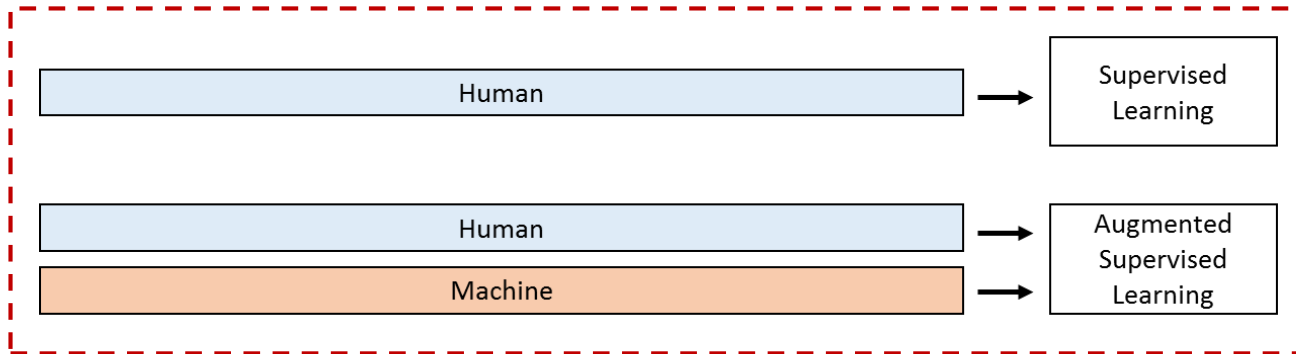
Machine Learning from Human and Machine

“Teachers”

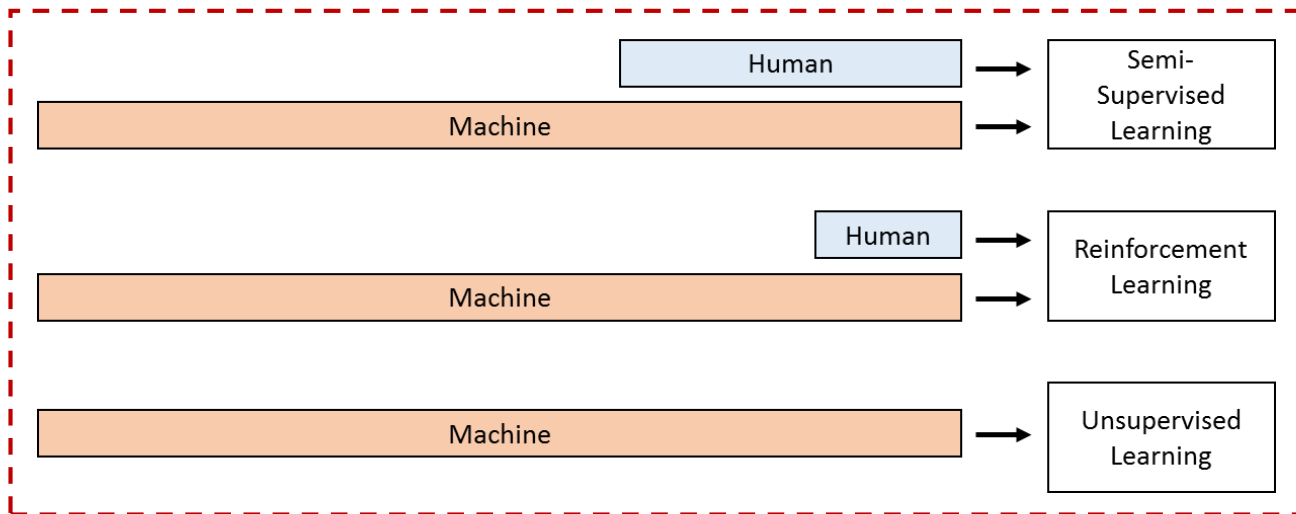
“Students”



Machine Learning from Human and Machine



Memorization



Understanding

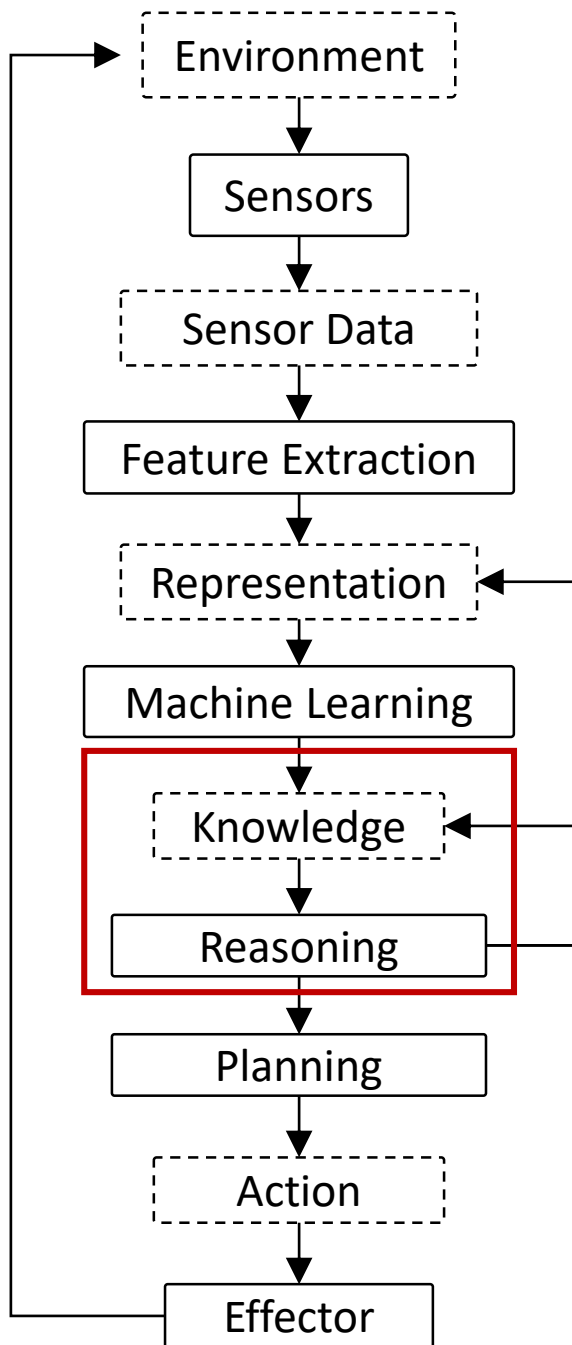


Image Recognition:
If it looks like a duck



Audio Recognition:
Quacks like a duck



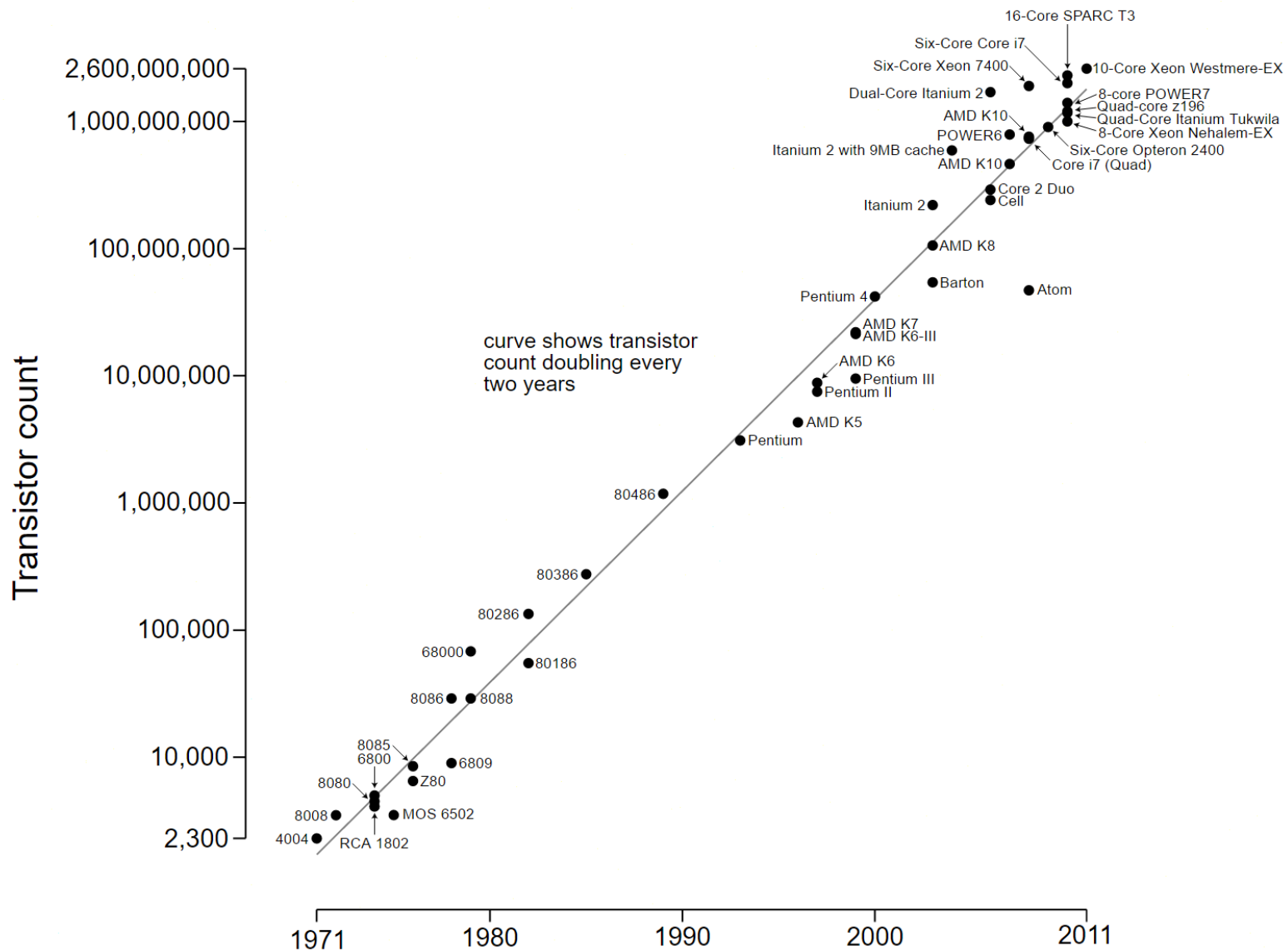
Activity Recognition:
Swims like a duck



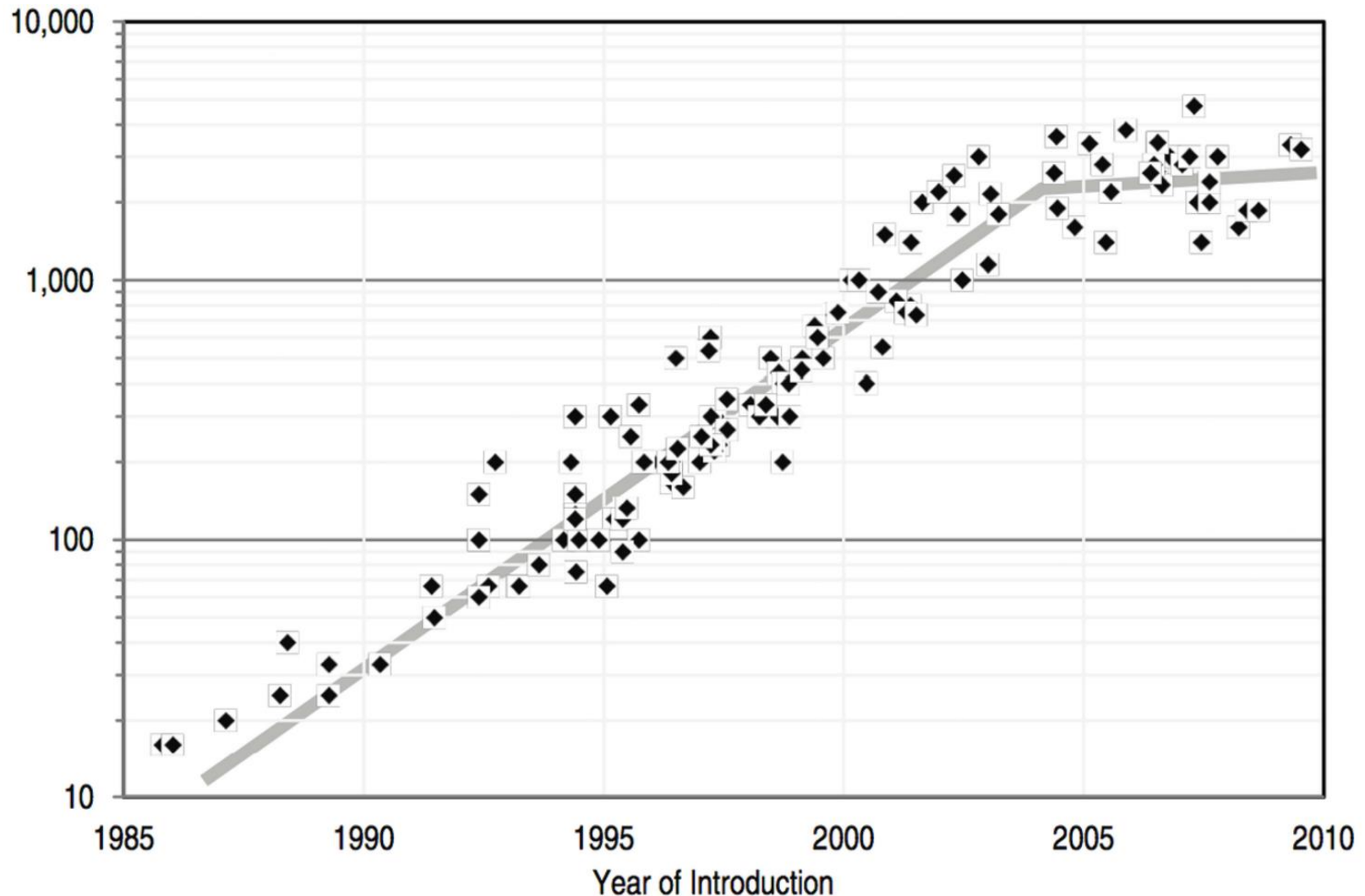
Challenge and Opportunity:

Compute

Microprocessor Transistor Counts 1971-2011 & Moore's Law



National Academy of Sciences: Clock Speed (MHz) Scaling Hits a Wall

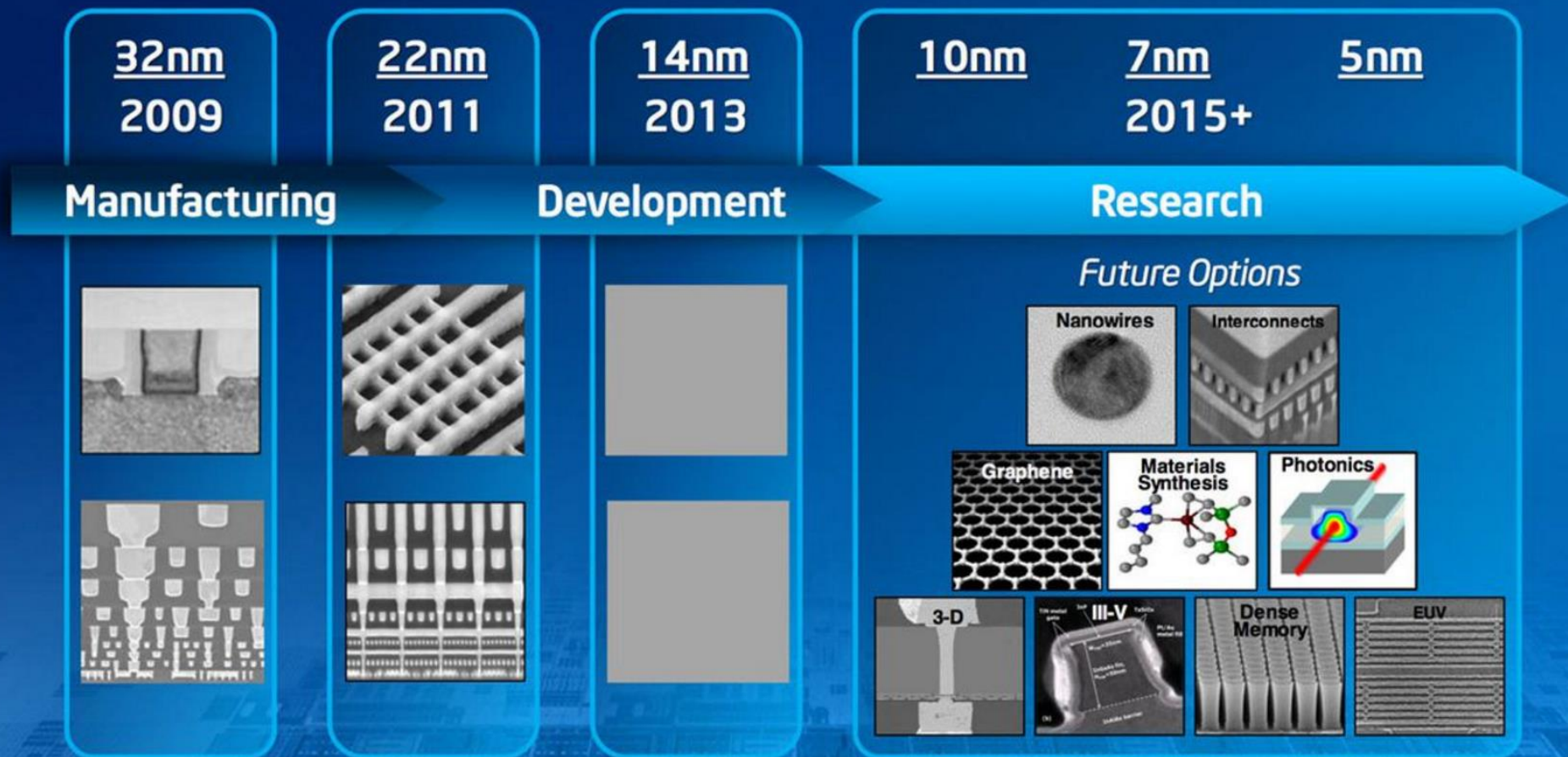


Intel: Innovation Continues

(Aggressively Solving Technical Challenges)

Innovation Enabled Technology Pipeline

Our Visibility Continues to Go Out ~10 Years



Beyond Moore's Law: Machine Learning Massive Parallelism & Distributed Compute

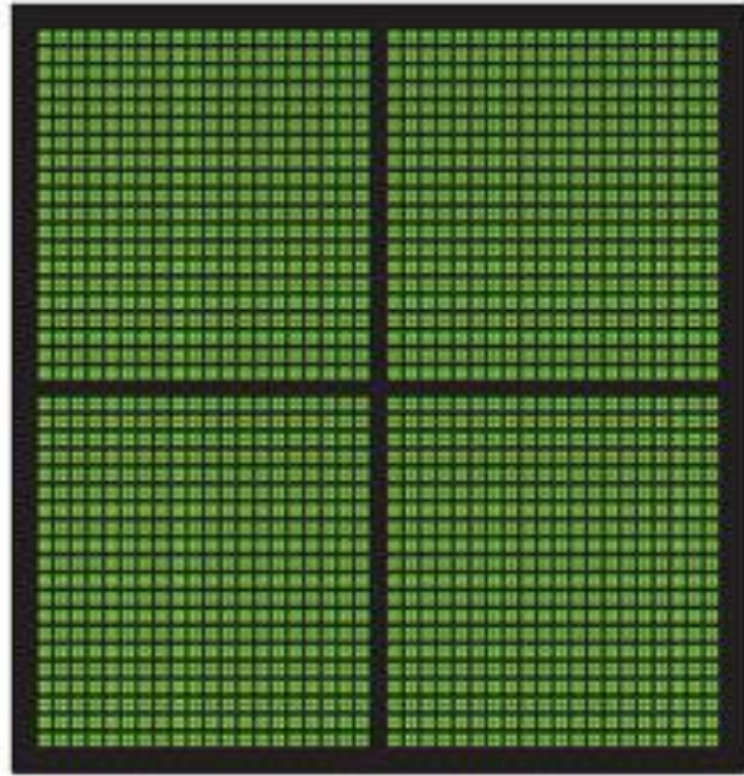


Beyond Moore's Law: Machine Learning

Graphics Processing Unit (GPU) Parallelism

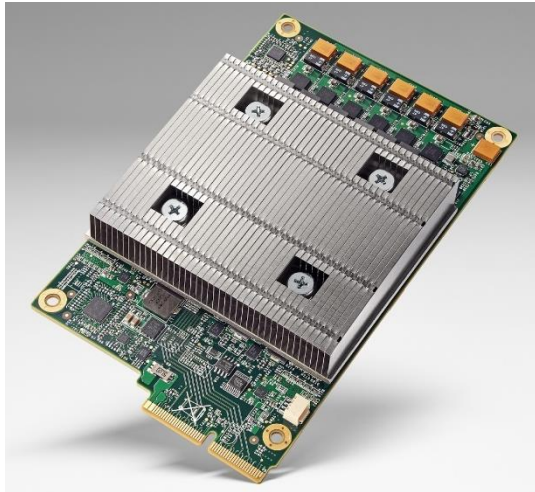


CPU
MULTIPLE CORES



GPU
THOUSANDS OF CORES

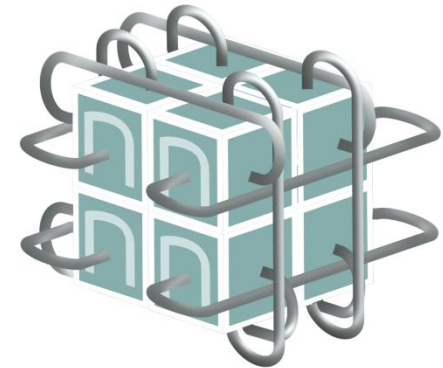
Beyond Moore's Law: Machine Learning Custom Deep Neural Network Chips



Google Tensor
Processing Unit



IBM True North
(Brain-Inspired Chip)

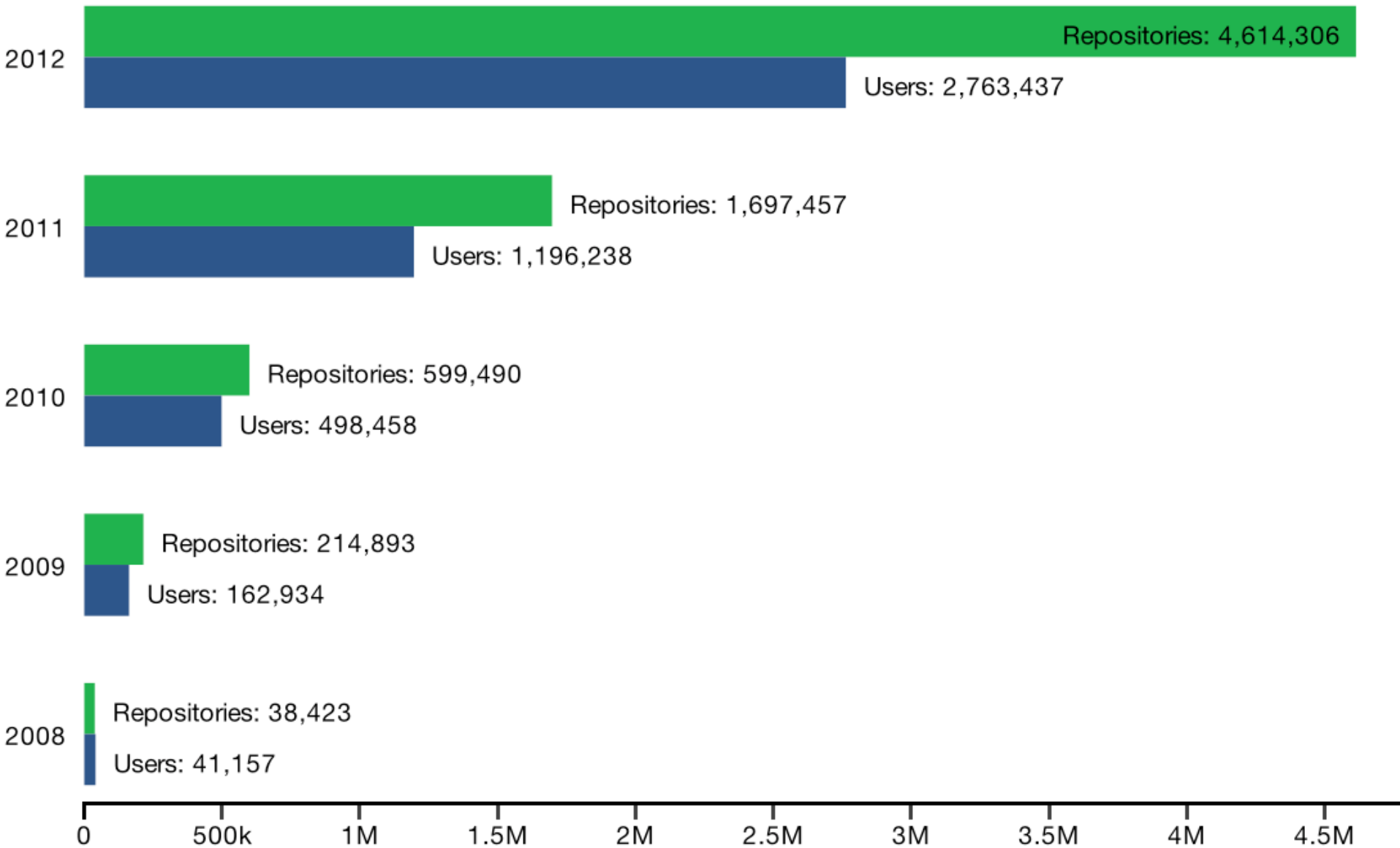


Intel Deep Learning Chip
(Nervana Acquisition)

Challenge and Opportunity:

Community

GitHub Growth



DeepTraffic

Americans spend 8 billion hours stuck in traffic every year.

Deep neural networks can help!

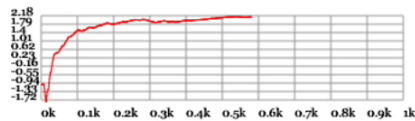
```
1
2 //<![CDATA[
3 // a few things don't have var in front of them - they update already
  existing variables the game needs
4 lanesSide = 1; //1;
5 patchesAhead = 10; //13;
6 patchesBehind = 0; //7;
7 trainIterations = 100000;
8
9 // begin from convnetjs example
10 var num_inputs = (lanesSide * 2 + 1) * (patchesAhead + patchesBehind);
11 var num_actions = 5;
12 var temporal_window = 3; //1 // amount of temporal memory. 0 = agent lives
   in-the-moment :)
13 var network_size = num_inputs * temporal_window + num_actions *
```

Apply Code/Reset Net

Save Code/Net to File

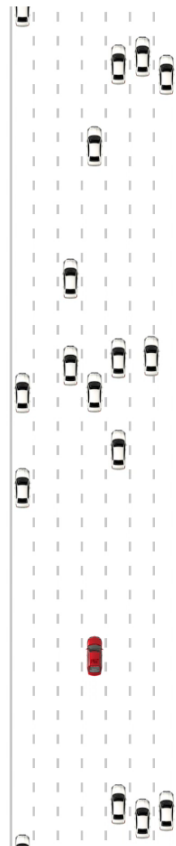
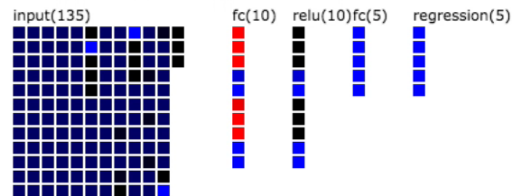
Load Code/Net from File

Submit Model to Competition



Start Evaluation Run

Value Function Approximating Neural Network:



Speed:
80 mph
Cars Passed:
290

Road Overlay:

None

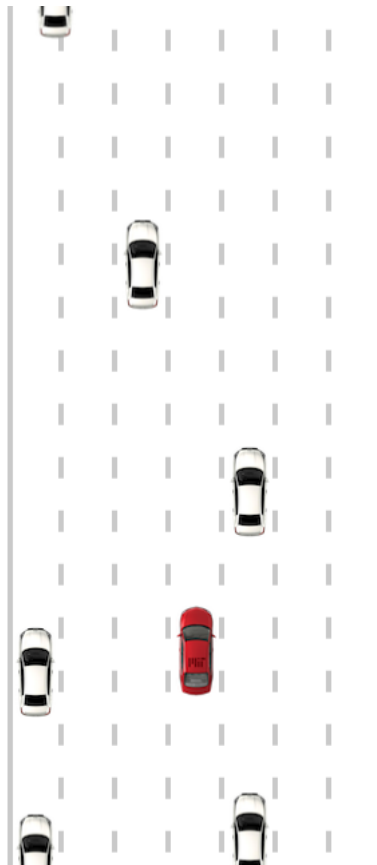
Simulation Speed:

Normal

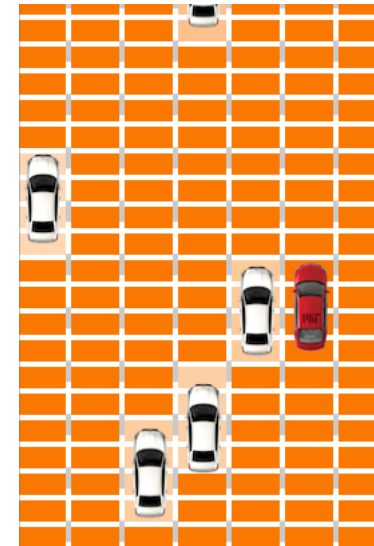
<http://cars.mit.edu>

The Road, The Car, The Speed

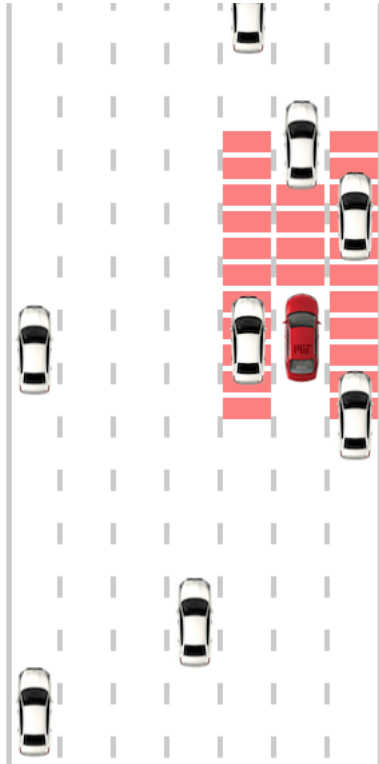
Speed:
47 mph
Cars Passed:
5



State Representation:

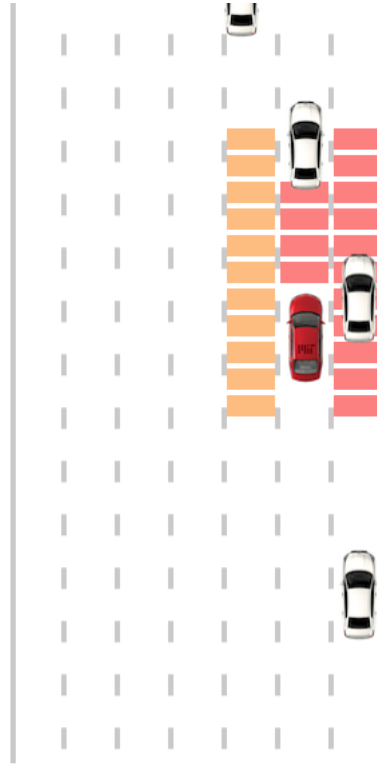


“Safety System”



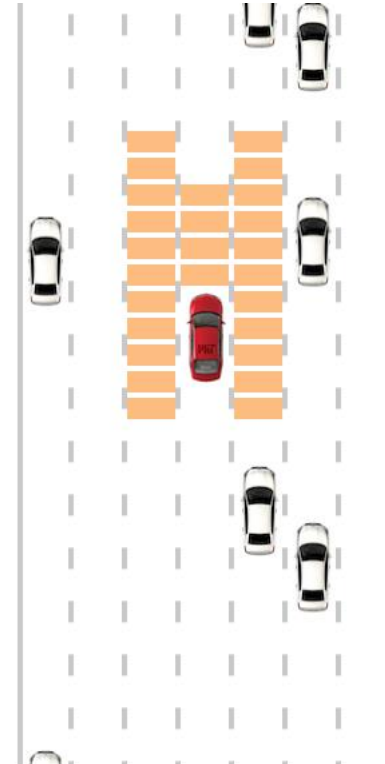
Road Overlay:

Safety System ⬆



Road Overlay:

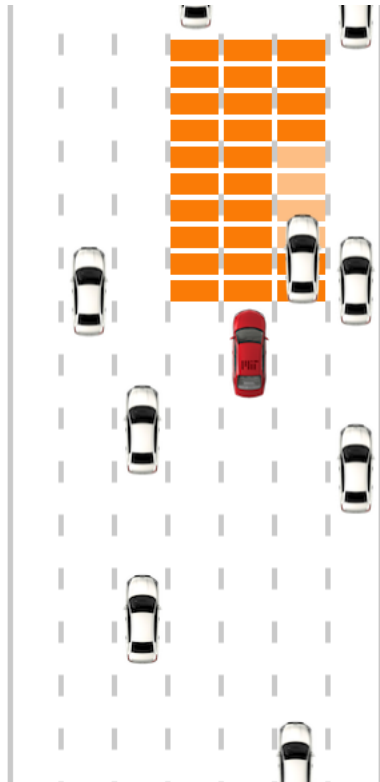
Safety System ⬆



Road Overlay:

Safety System ⬆

Learning Input

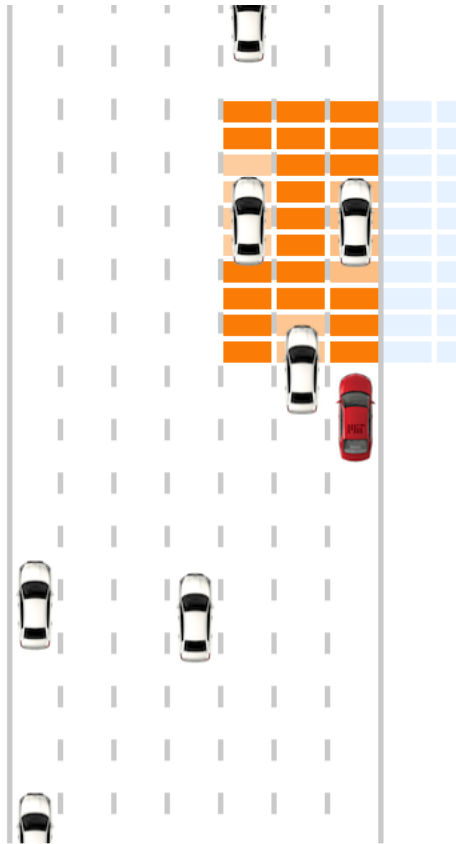


Road Overlay:

Learning Input ↕

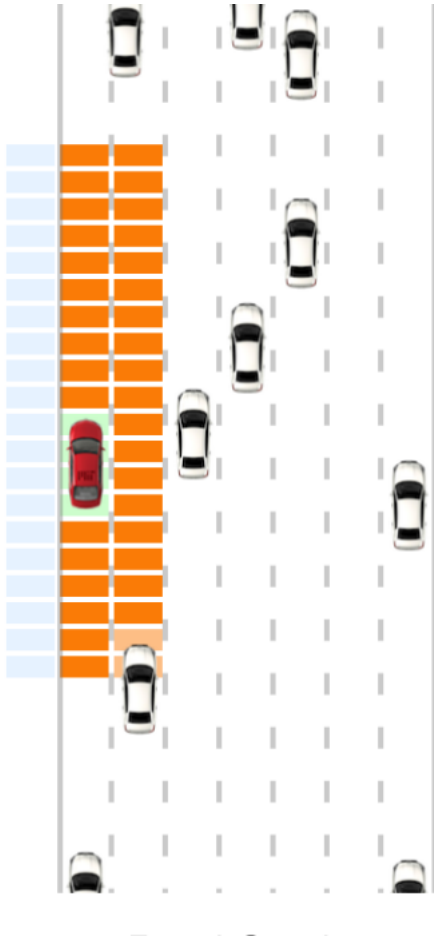
```
lanesSide = 1;  
patchesAhead = 10;  
patchesBehind = 0;
```

Learning Input



```
lanesSide = 2;  
patchesAhead = 10;  
patchesBehind = 0;
```

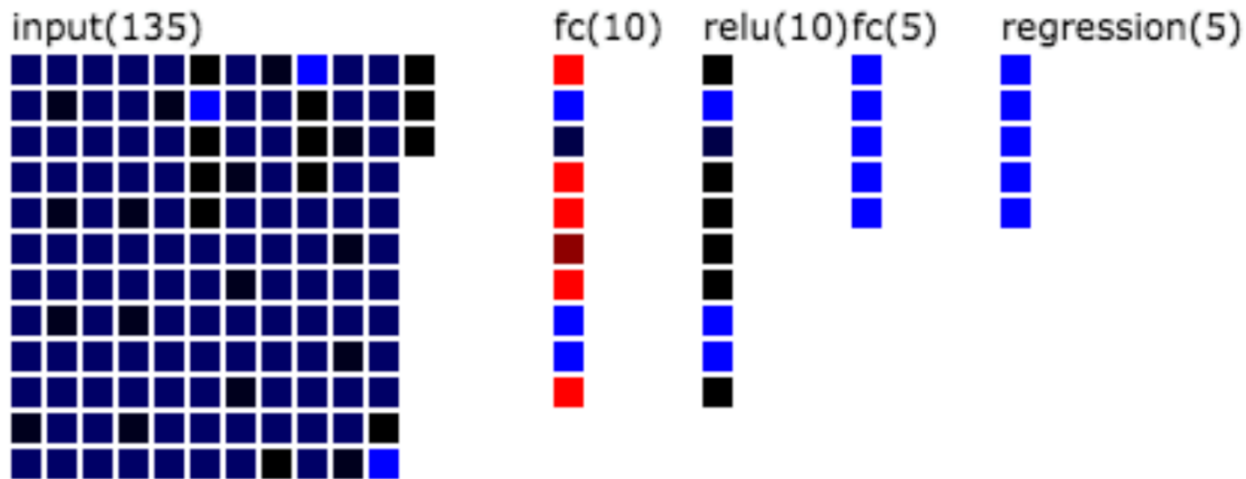
Learning Input



```
lanesSide = 1;  
patchesAhead = 10;  
patchesBehind = 10;
```


Deep RL: Q-Function Learning Parameters

Value Function Approximating Neural Network:



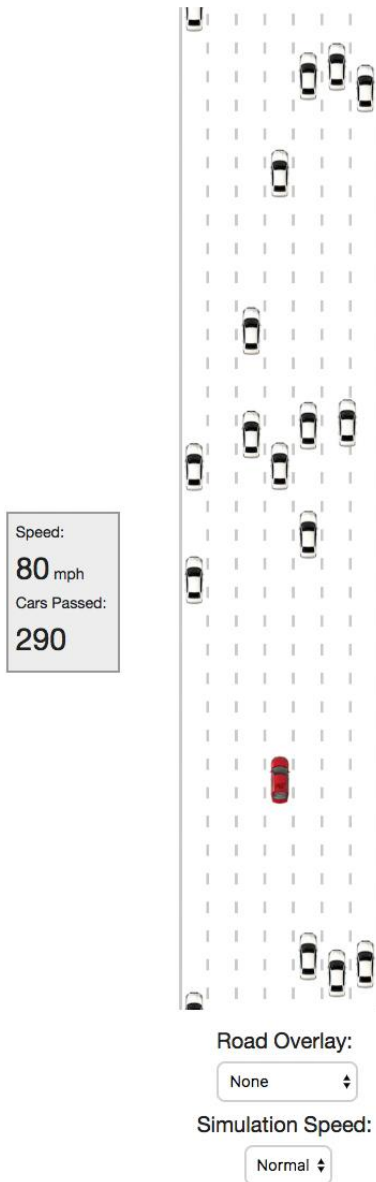
```
var num_inputs = (lanesSide * 2 + 1) * (patchesAhead + patchesBehind);  
var num_actions = 5;  
var temporal_window = 3;  
var network_size = num_inputs * temporal_window + num_actions *  
temporal_window + num_inputs;
```

DeepTraffic

<http://cars.mit.edu>

We ran a competition, and in one month:

- 250 submission from MIT
- 10,000+ submissions from outside MIT



DeepTraffic

<http://cars.mit.edu>

In MIT



Purnawirman (74.48 mph)

Winnings: [Deep Learning book \(Goodfel](#)

Comment: "I used a single hidden layer. window as 0). Spent some time on hyper times, because the test scores have a big



Michael Gump (74.04 mph)

Winnings: [Udacity Self-Driving Car Engin](#)

Comment: "I mainly played around with would get stuck in suboptimal strategies



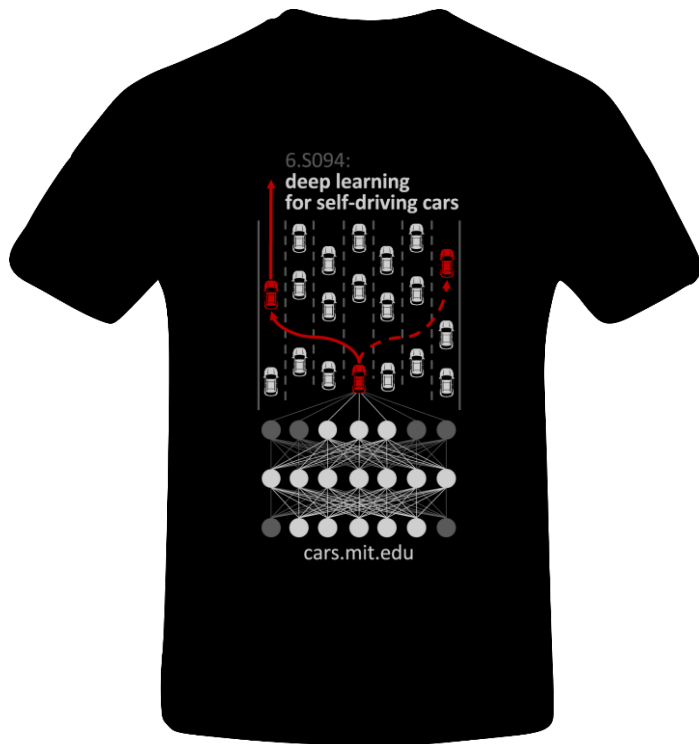
Jeffrey Hu (73.59 mph)

Winnings: [Udacity Self-Driving Car Engin](#)

Comment: "I preprocessed to reduce the layer fully connected network. Then I trie get the network to converge."

Outside MIT

User	MPH
Hoan Nguyen	76.29
lorcus96	76.16
leiming yu	75.97
jordan ott	75.86
Nándor Kedves	75.83
3upperm2n	75.80
Mark S.	75.73
Diego Rojo U-tad	75.69
katypiano	75.62



DeepTraffic

<http://cars.mit.edu>

Challenge to GBAIR Students:
Make a neural network
that travels 70+ mph.

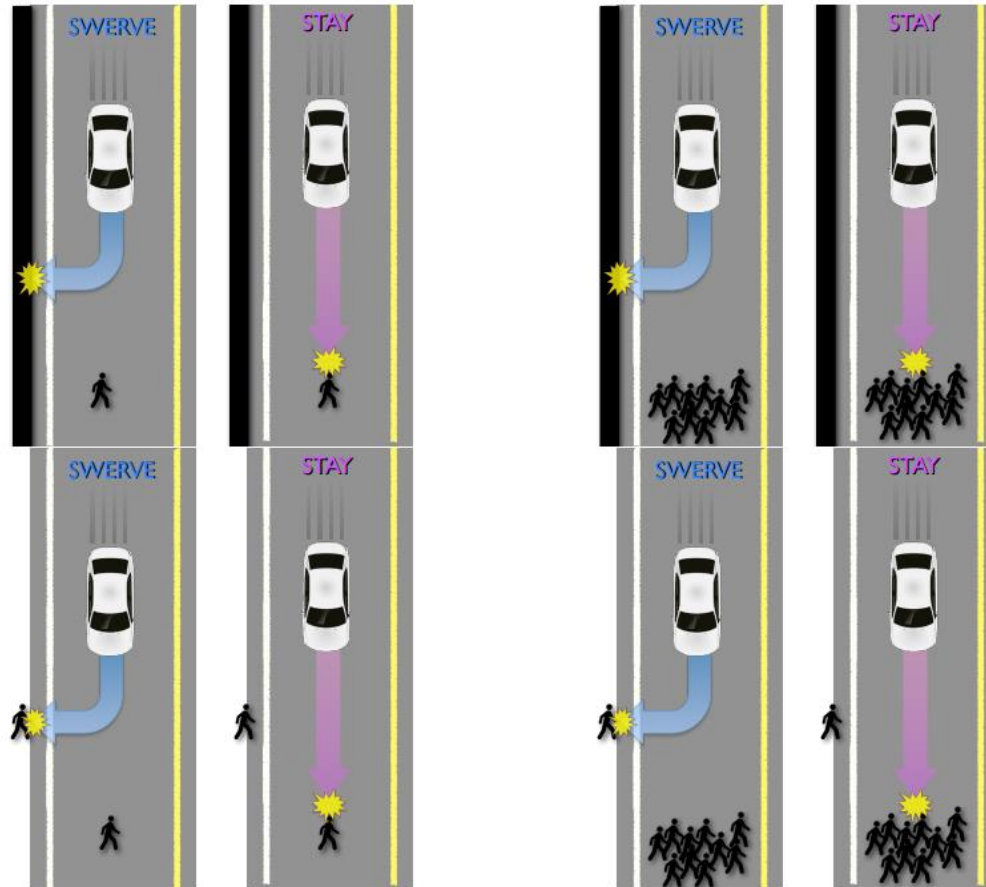
Challenge and Opportunity:

Reward Function

(aka Ethics)

Defining a Good Reward Function is Difficult

This example is popular but is not an engineering challenge as it's faced by both humans and machines alike.



Instead, we want to answer the engineering question...



Defining a Good Reward Function is Difficult



Coast Runners: Discovers local pockets of high reward ignoring the “implied” bigger picture goal of finishing the race.

All references cited in this presentation are listed in the following Google Sheets file: <https://goo.gl/wDHwnU>

Question?

